

# Validation of SSI datasets

*On the long term*

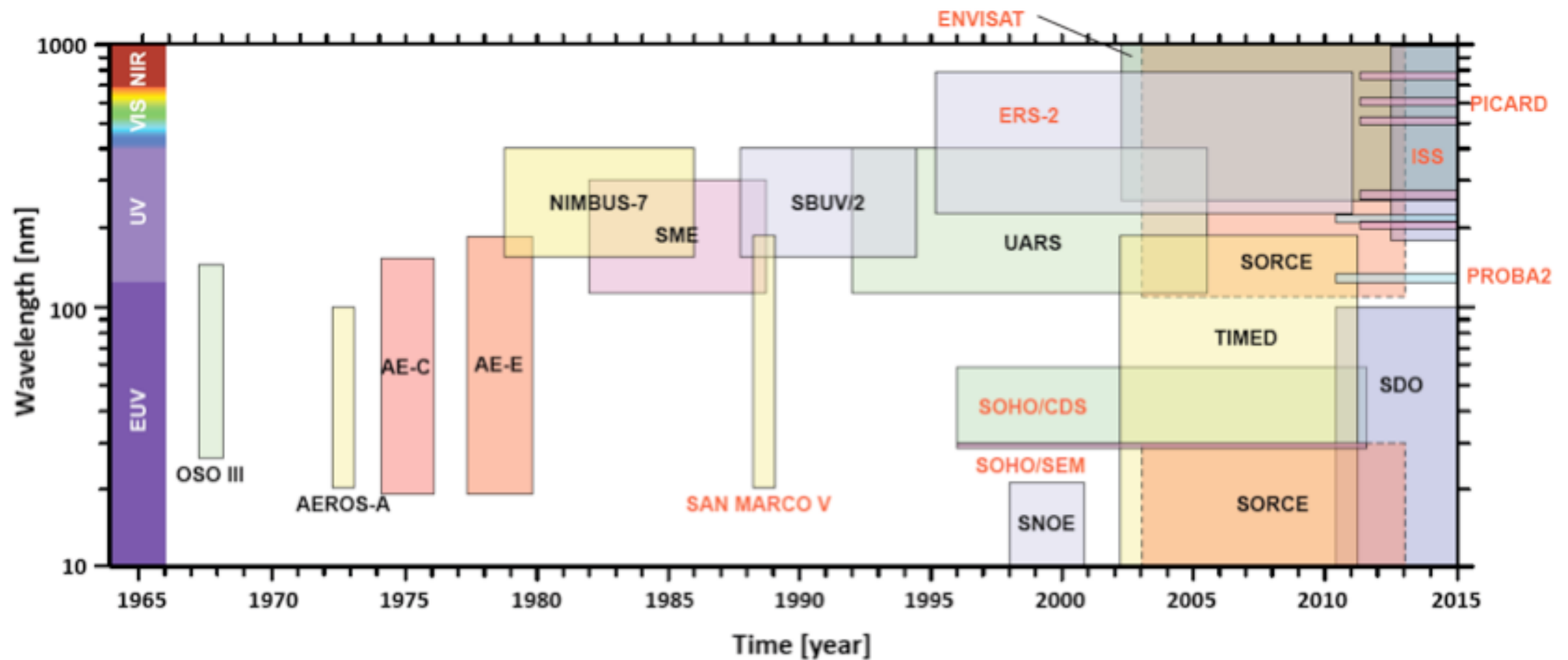
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# SSI Measurements



- What are the uncertainties on these time series ?

# Measuring SSI

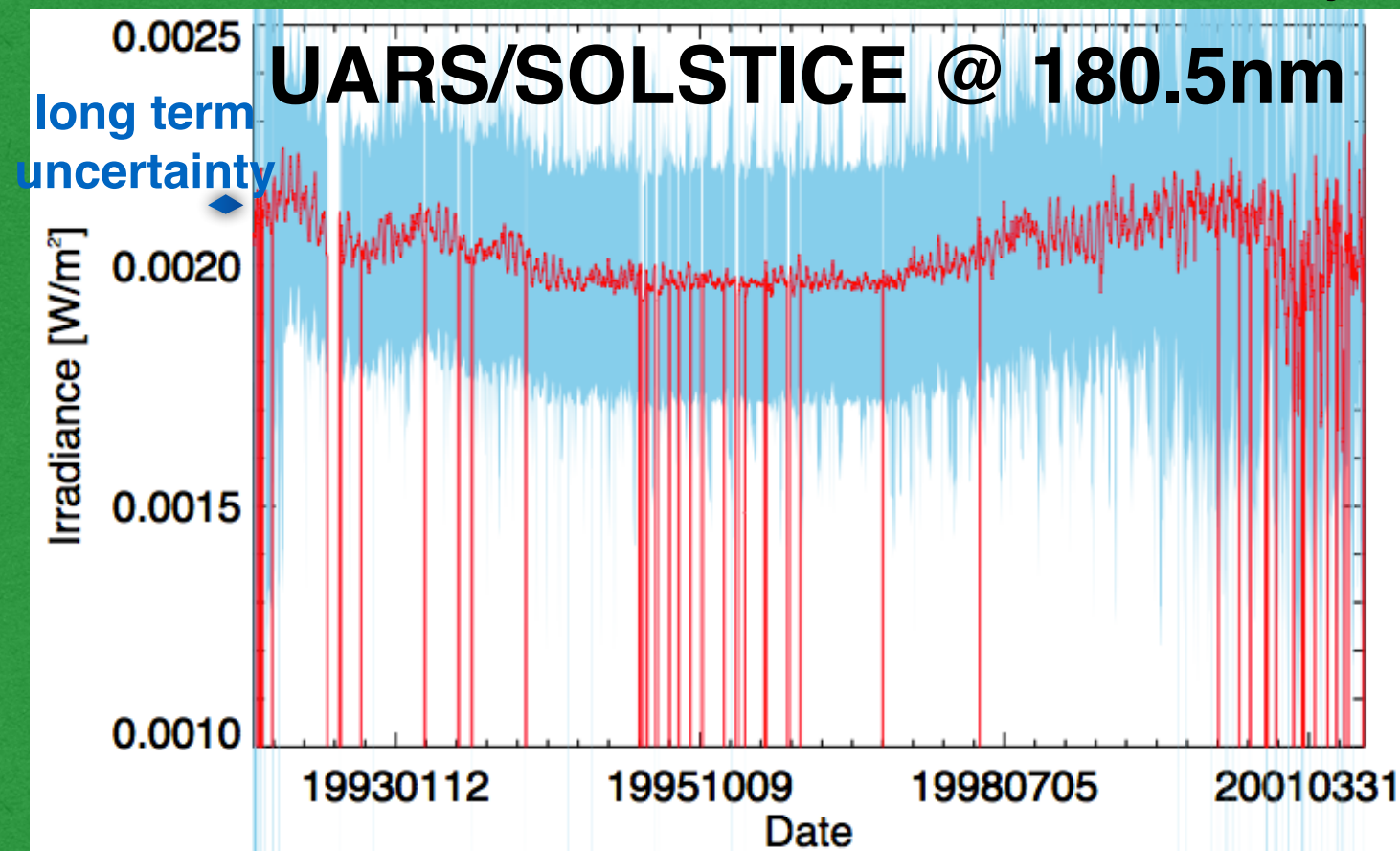
*True irradiance*  $h\nu$  ↓

**INSTRUMENT**

On board monitoring system:  
degradation + others

Ground  
calibration & processing

*Measured irradiance + Uncertainty*



NB: accuracy or long term uncertainty

# Measuring SSI

*True irradiance*  $h\nu$  ↓

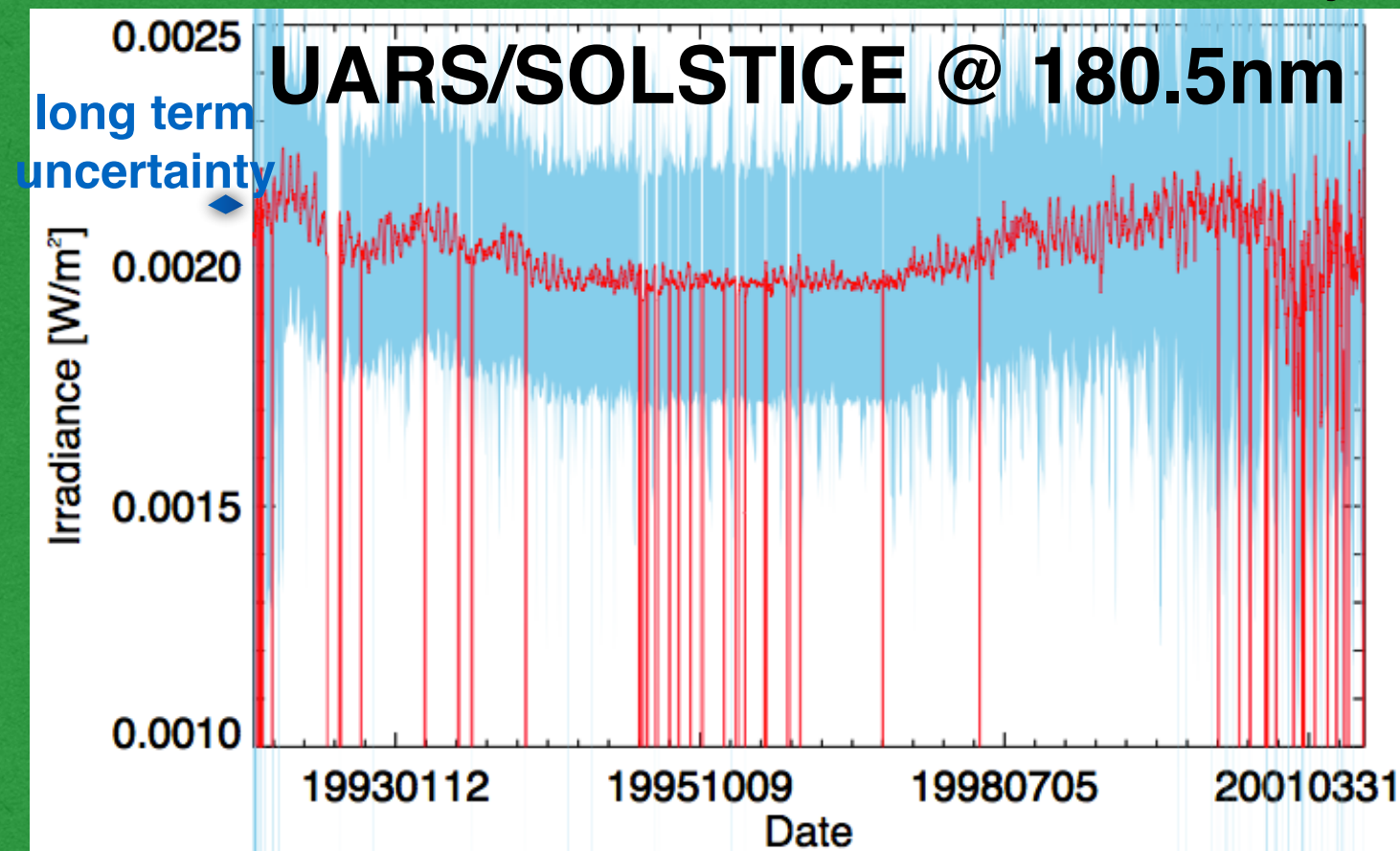
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On board monitoring system:  
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# Measuring SSI

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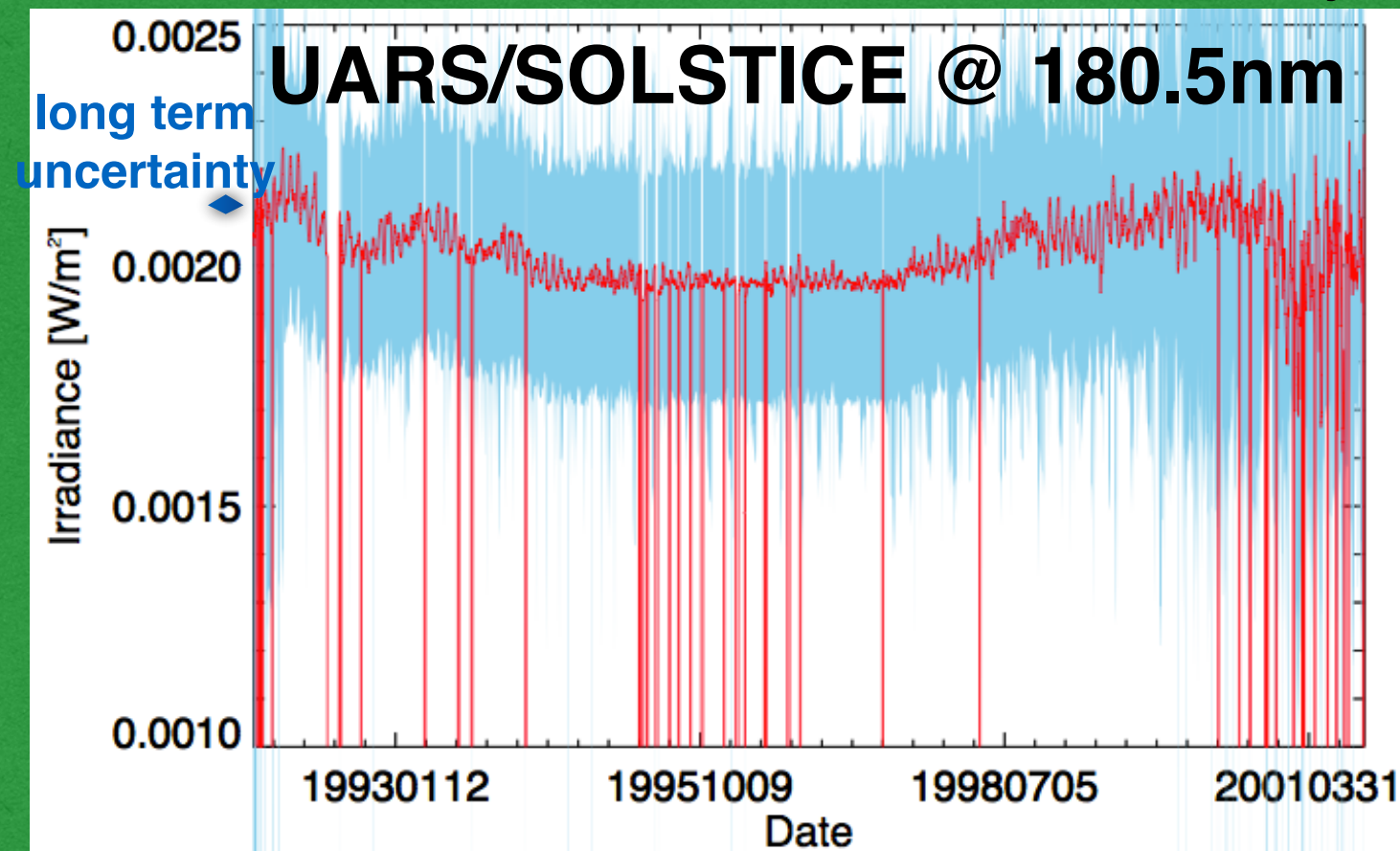
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## Measured irradiance + Uncertainty



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## COMMUNITY

Analysis/Comparison with  
other instruments, models,  
solar proxies, and all  
(almost) you can imagine

# Measuring SSI

*True  
irradiance*  
 $h\nu$

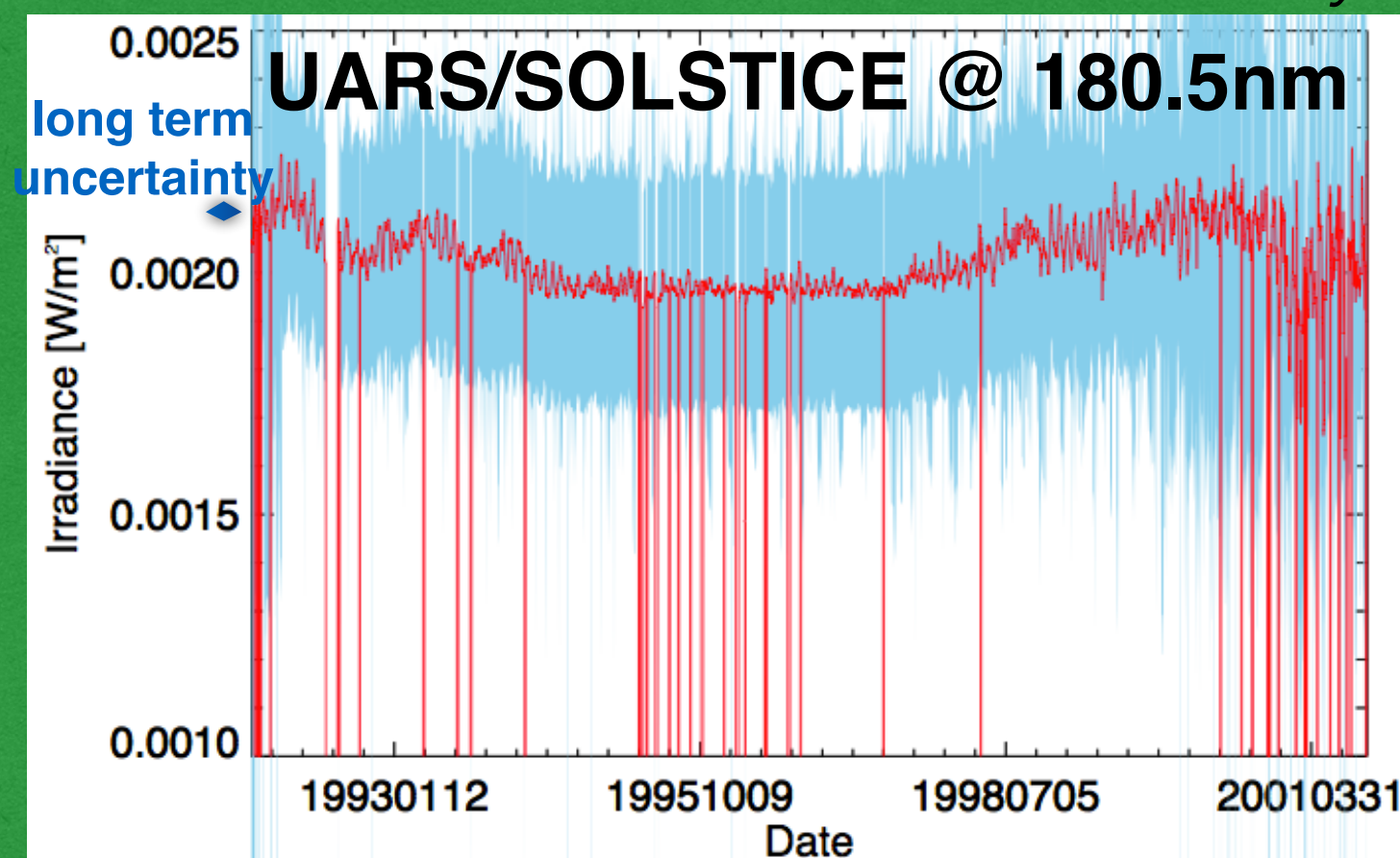
**INSTRUMENT**

On board monitoring system:  
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$$R(t_1, t_2) = \frac{I(t_2)}{I(t_1)} \quad U(R)?$$

**Measured irradiance + Uncertainty**



NB: accuracy or long term uncertainty



# Measuring SSI

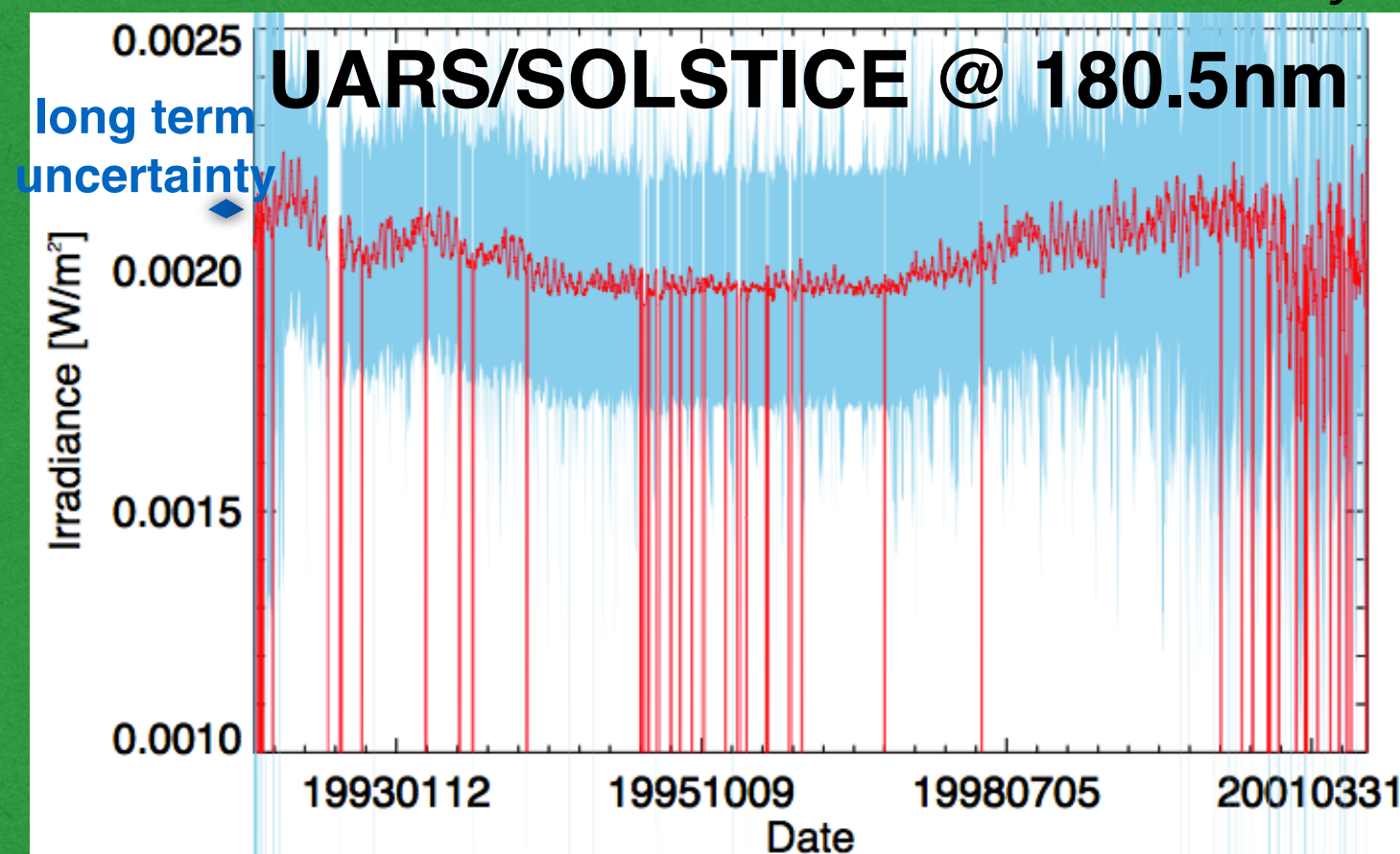
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*Measured irradiance + Uncertainty*



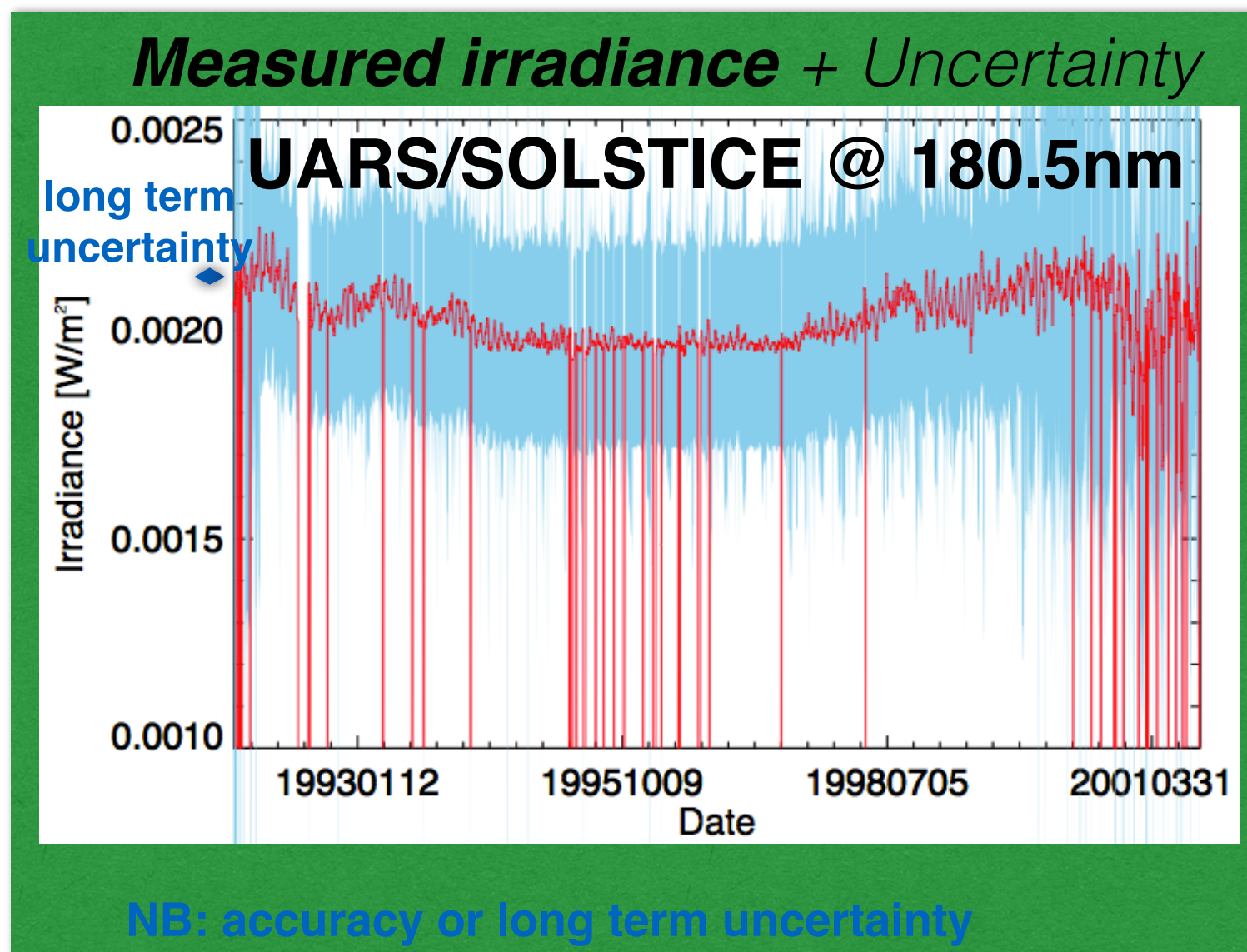
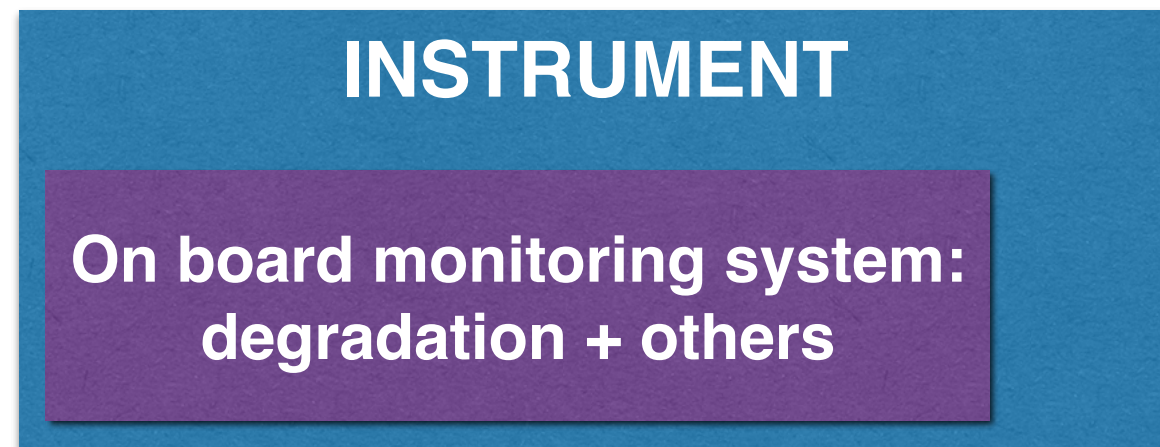
NB: accuracy or long term uncertainty

$$R(t_1, t_2) = \frac{I(t_2)}{I(t_1)} \quad U(R)?$$

~~$$\frac{U(R)}{R} = \sqrt{\left(\frac{U(I(t_1))}{I(t_1)}\right)^2 + \left(\frac{U(I(t_1))}{I(t_1)}\right)^2}$$~~

# Measuring SSI

True irradiance  $h\nu$  ↓



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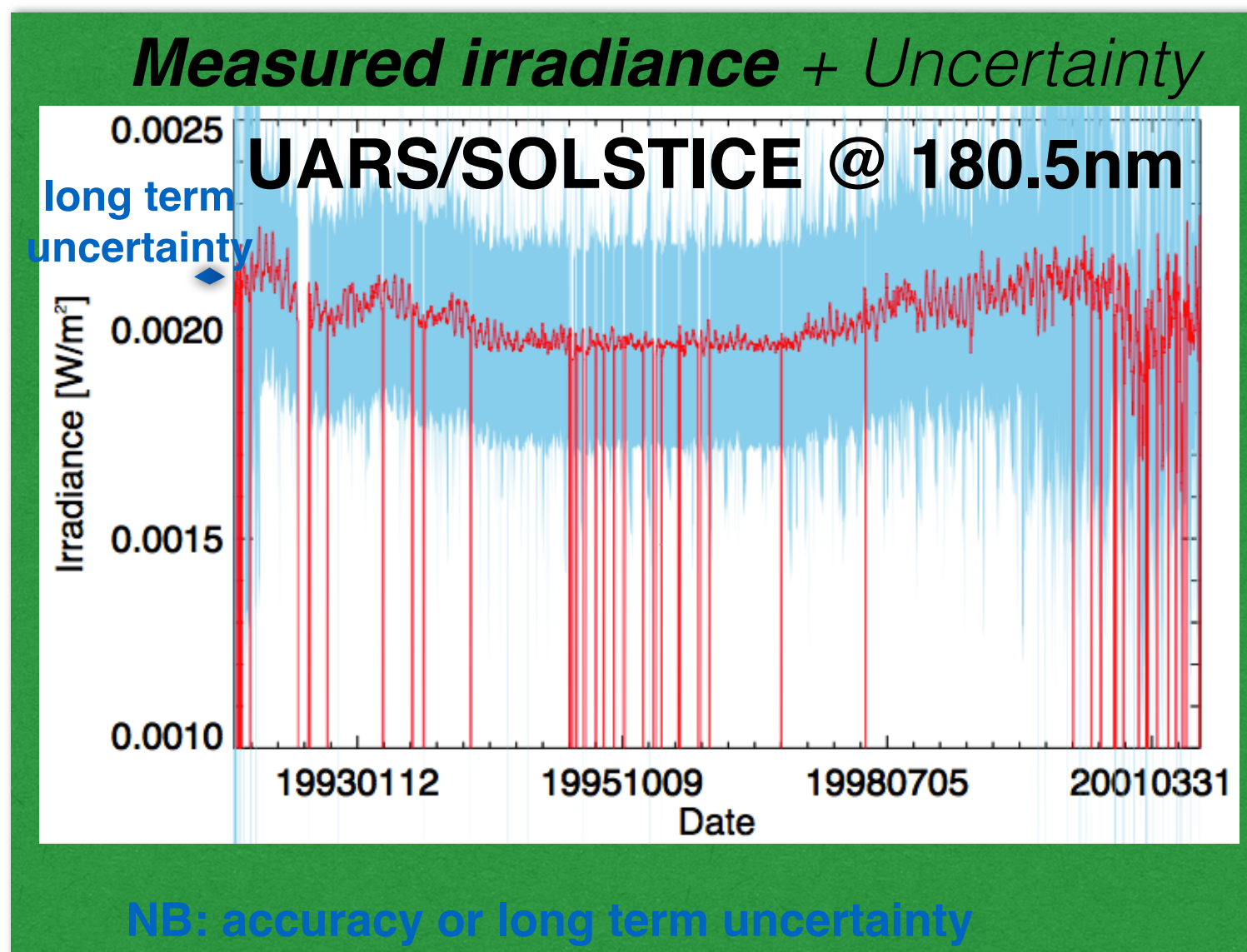
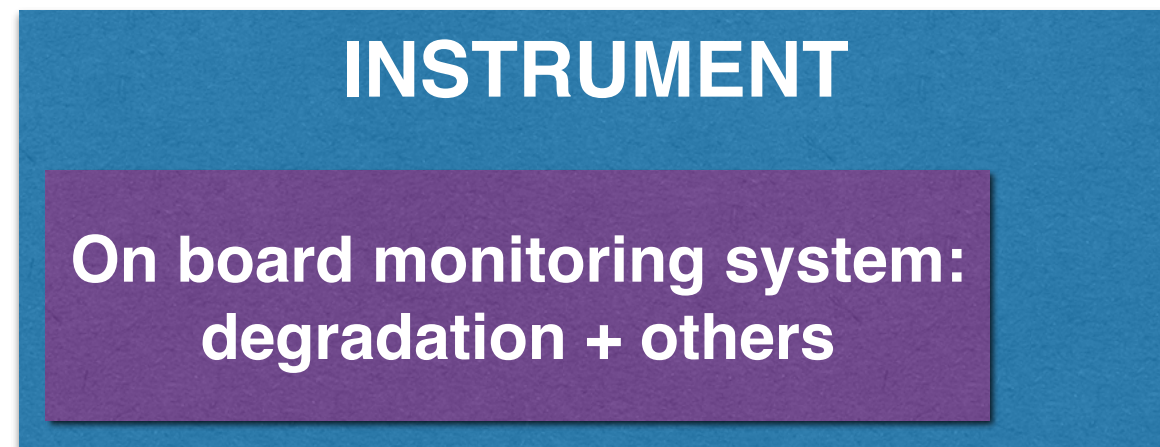
$$\frac{U(R(t_1, t_2))}{R(t_1, t_2)} = \int_{t_1}^{t_2} LTU(t) dt$$

$$\approx LTU \times (t_2 - t_1)$$



# Measuring SSI

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$$\approx LTU \times (t_2 - t_1)$$

Ideally,

LTU is in % (or ppm) / year

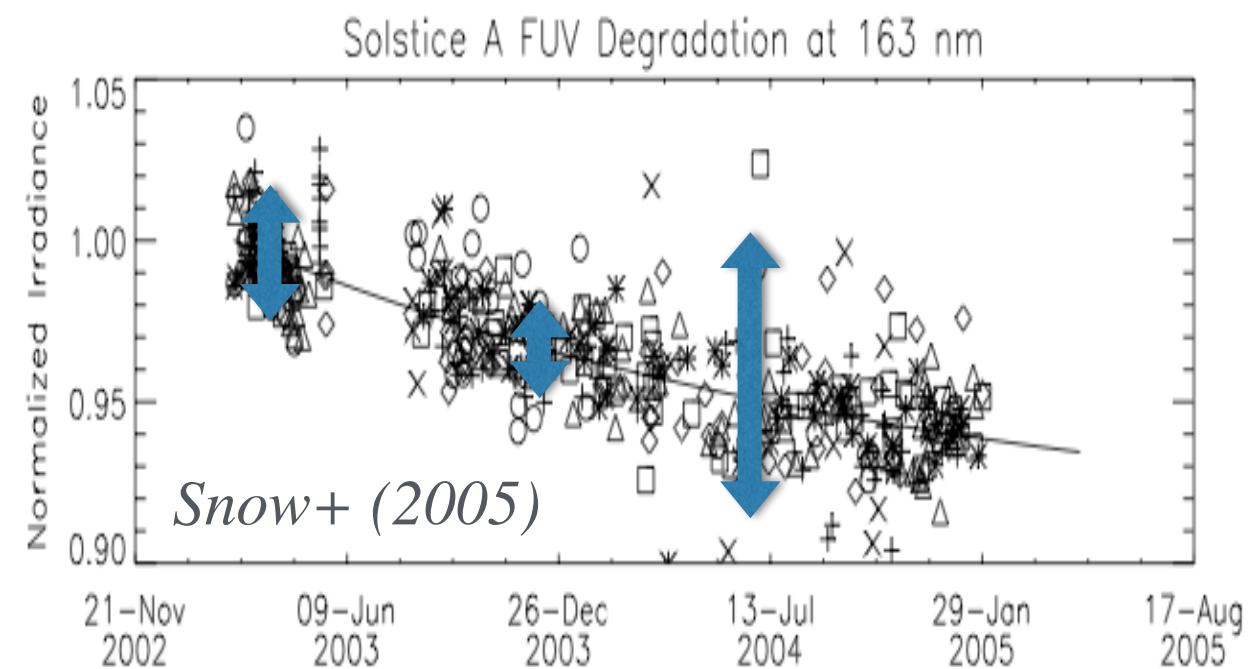
LTU is time dependent

# Long term uncertainty

$$I^{meas}(t) = I^{true}(t)g(t)$$

$$LTU \approx U(g(t)) \quad (\text{but not only})$$

- It is usually difficult from the instrument to give time-dependent long term accuracy.
- Old datasets (SME ?) has no LTU.
- Some have no independent LTU (SBUV)



→ **Aim: homogeneous assessment of long term uncertainties of all datasets**

# Validation / Comparison

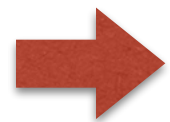
- What to compare with ?

- ➔ Other data
- ➔ Existing models (proxy based or semi empirical)
- ➔ proxies

# Validation / Comparison

- What to compare with ?

- ➔ Other data
- ➔ Existing models (proxy based or semi empirical)
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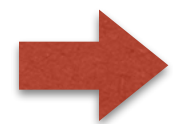
**Hyp. 1: proxies can reproduce ssi variations to a certain degree**



# Validation / Comparison

- What to compare with ?

- ➔ Other data
- ➔ Existing models (proxy based or semi empirical)
- ➔ **proxies**



Hyp. 1: proxies can reproduce ssi variations to a certain degree



Hyp. 2: assumed relationships between proxies and SSI

Method1

Method2

# The less restrictive The more permissive

- Each spectral time series of each datasets is fitted with a two time scale linear component model

SSI time series      LF (>108 days) proxies      HF (<108 days) proxies

$$I(\lambda, t) = a_0 + \sum_i a_{i,lf}(\lambda) P_{i,lf}(t) + a_{i,hf}(\lambda) P_{i,hf}(t) + \varepsilon$$

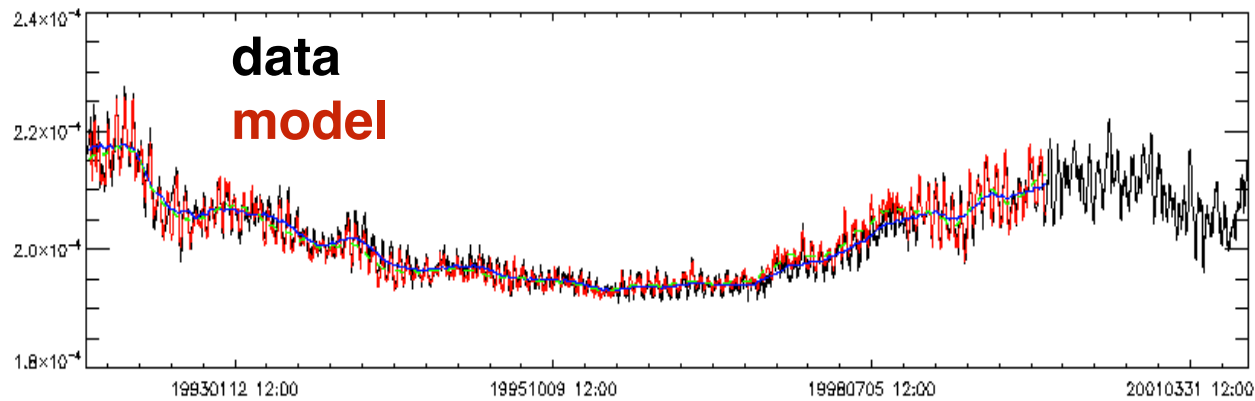
best model coefficients (lsq sense) determined for each  $\lambda$

- Used proxies:

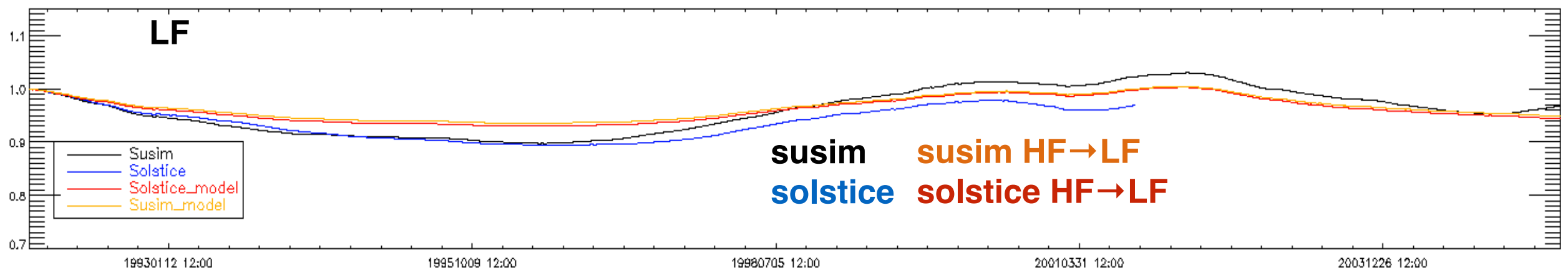
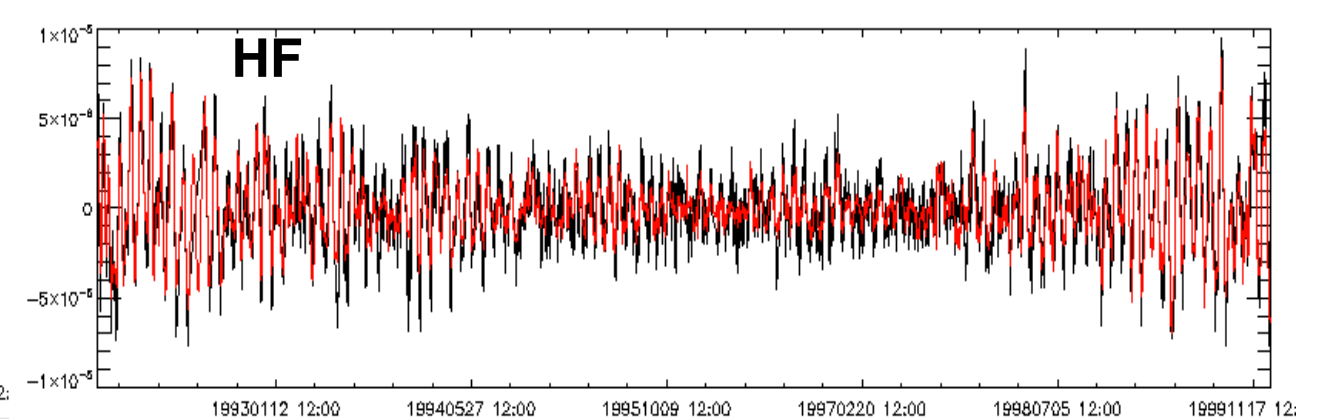
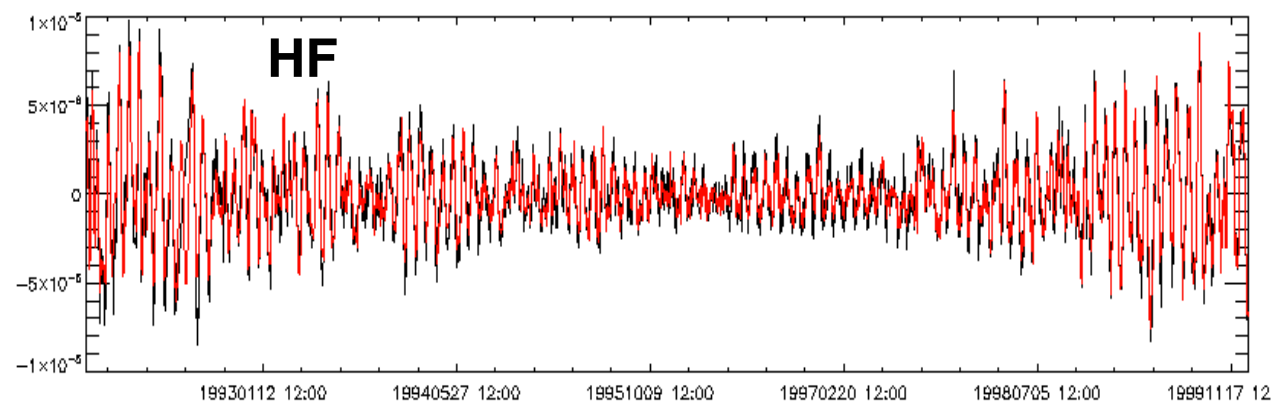
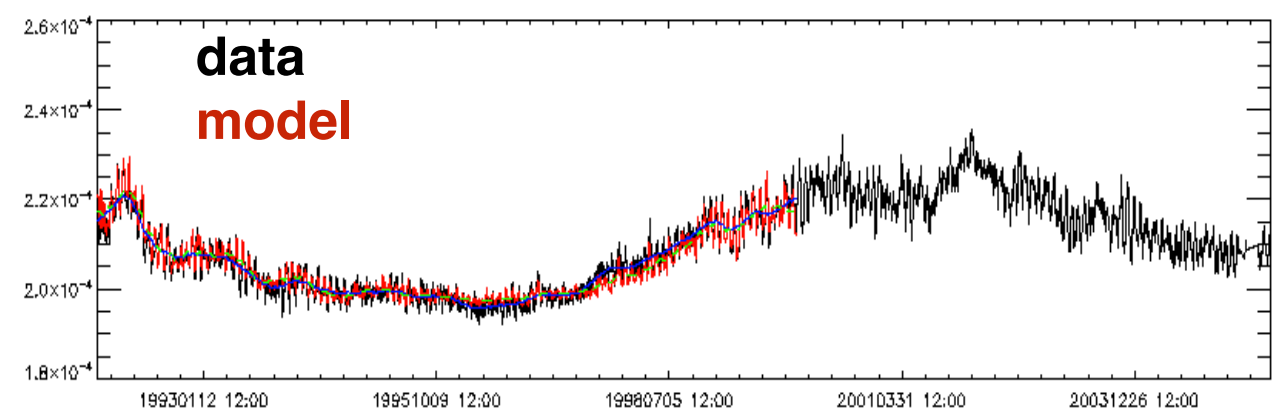
**DSA, Mg II, and radio fluxes at 3.2cm, 10.7cm, 15cm, 30cm.**

# Why two time-scales ?

**U/SOLSTICE@160nm**



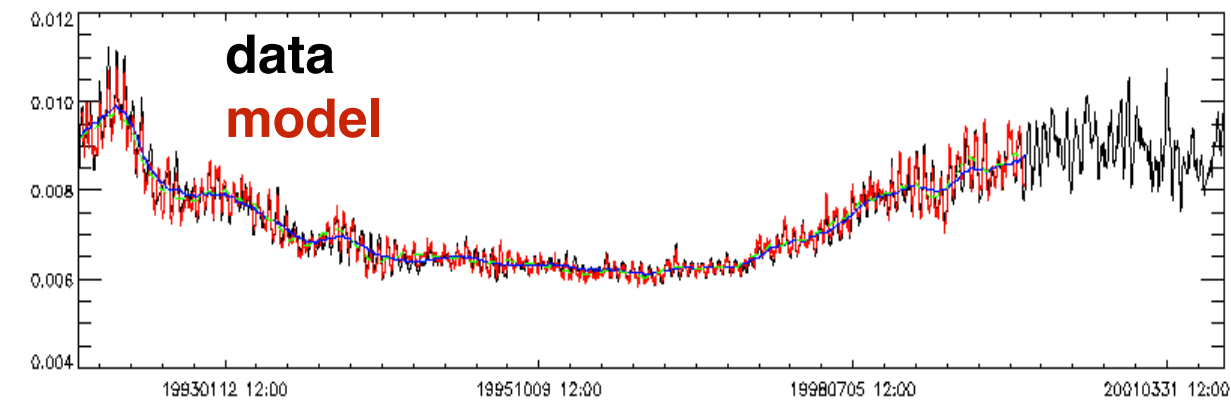
**U/SUSIM@160nm**



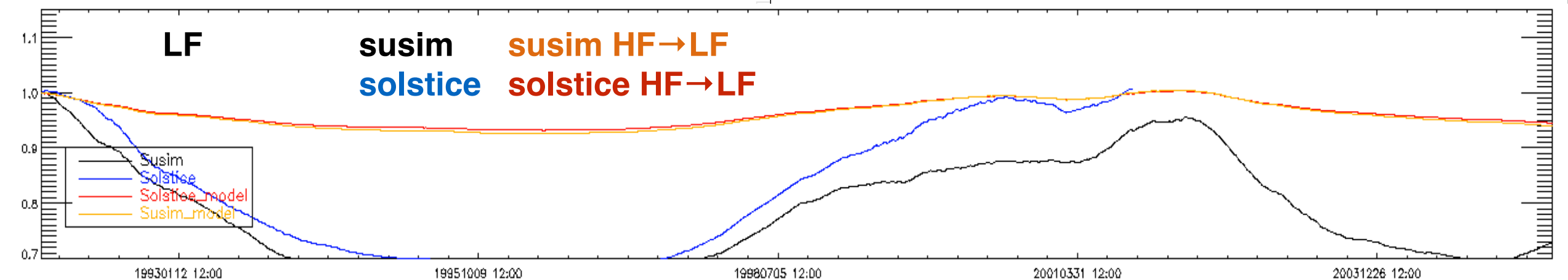
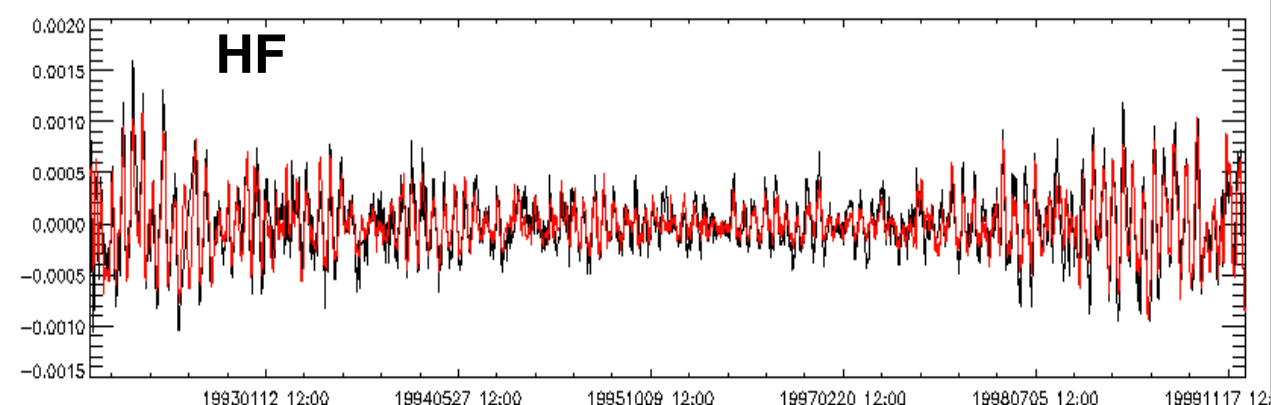
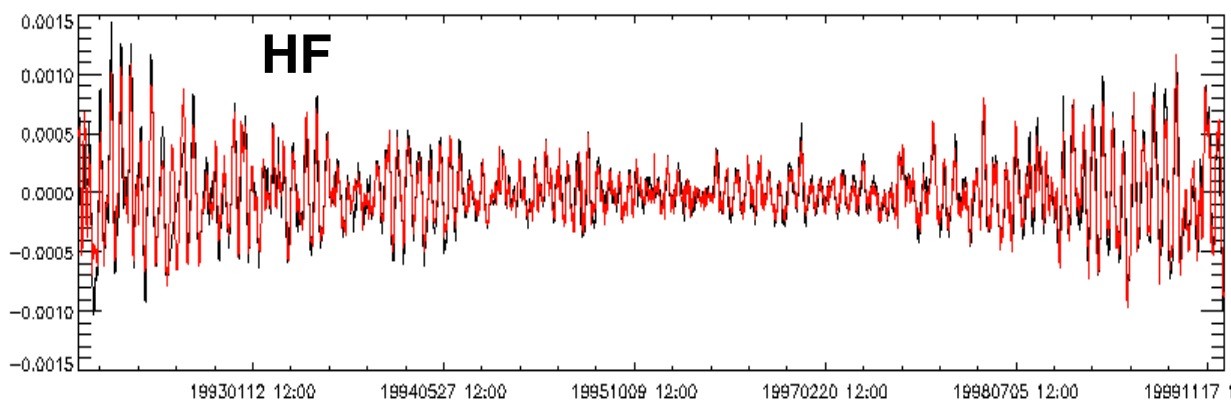
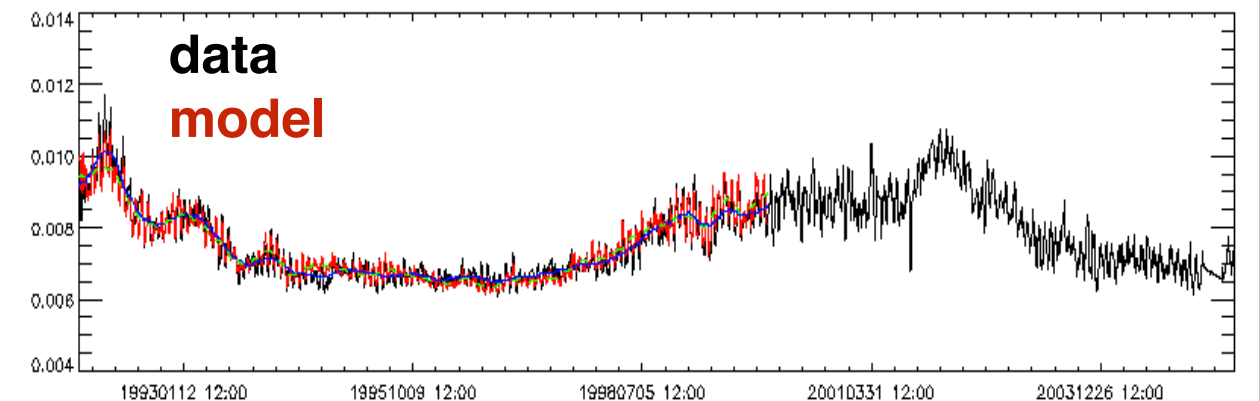
- Rotation amplitudes underestimates the cycle variations

# Why two time-scales ?

**U/SOLSTICE@Ly- $\alpha$**



**U/SUSIM@Ly- $\alpha$**



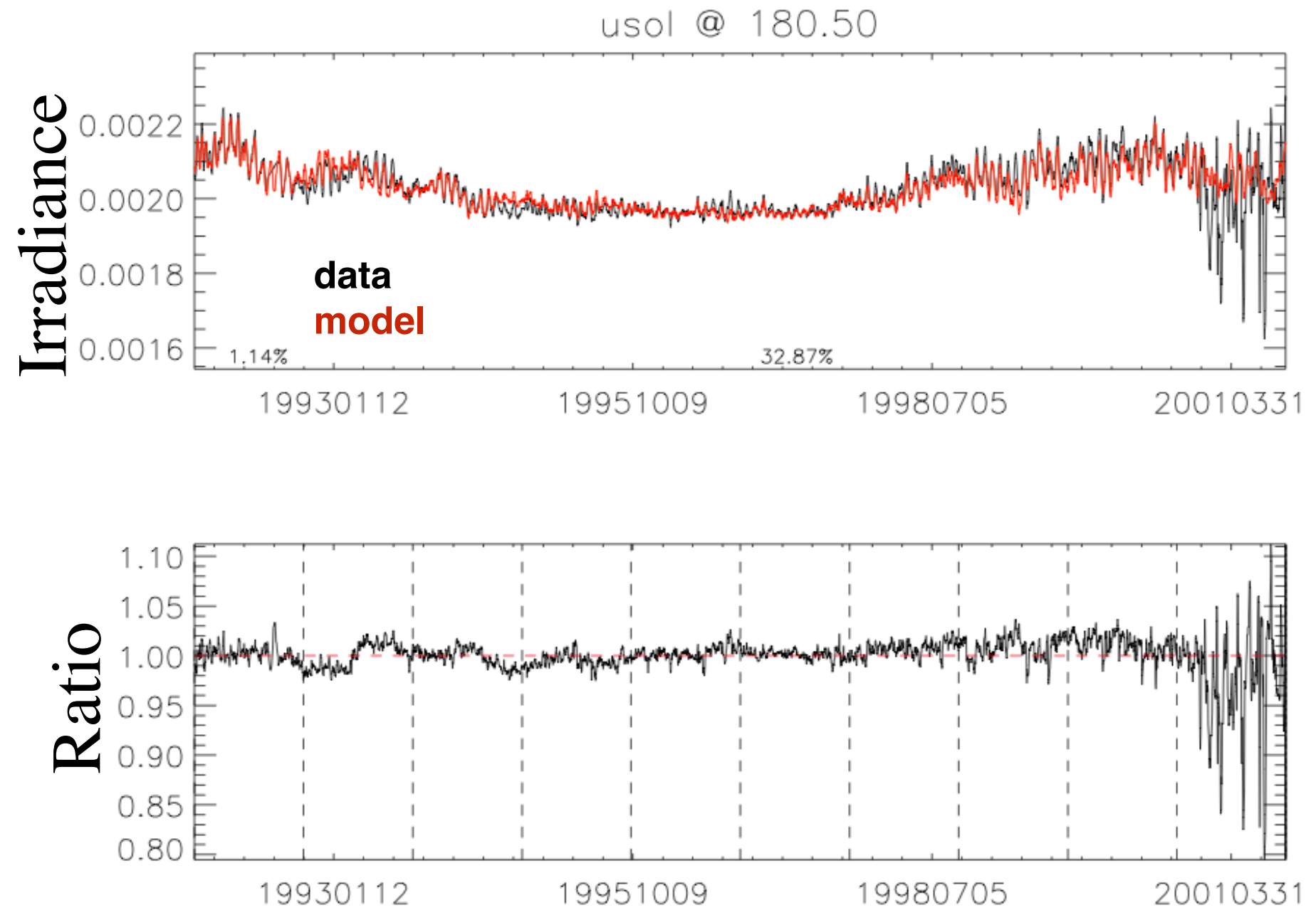
- Rotation amplitudes underestimates the cycle variations



# LTU: How does it work ?

*Example: UARS/Solstice @ 180.5nm*

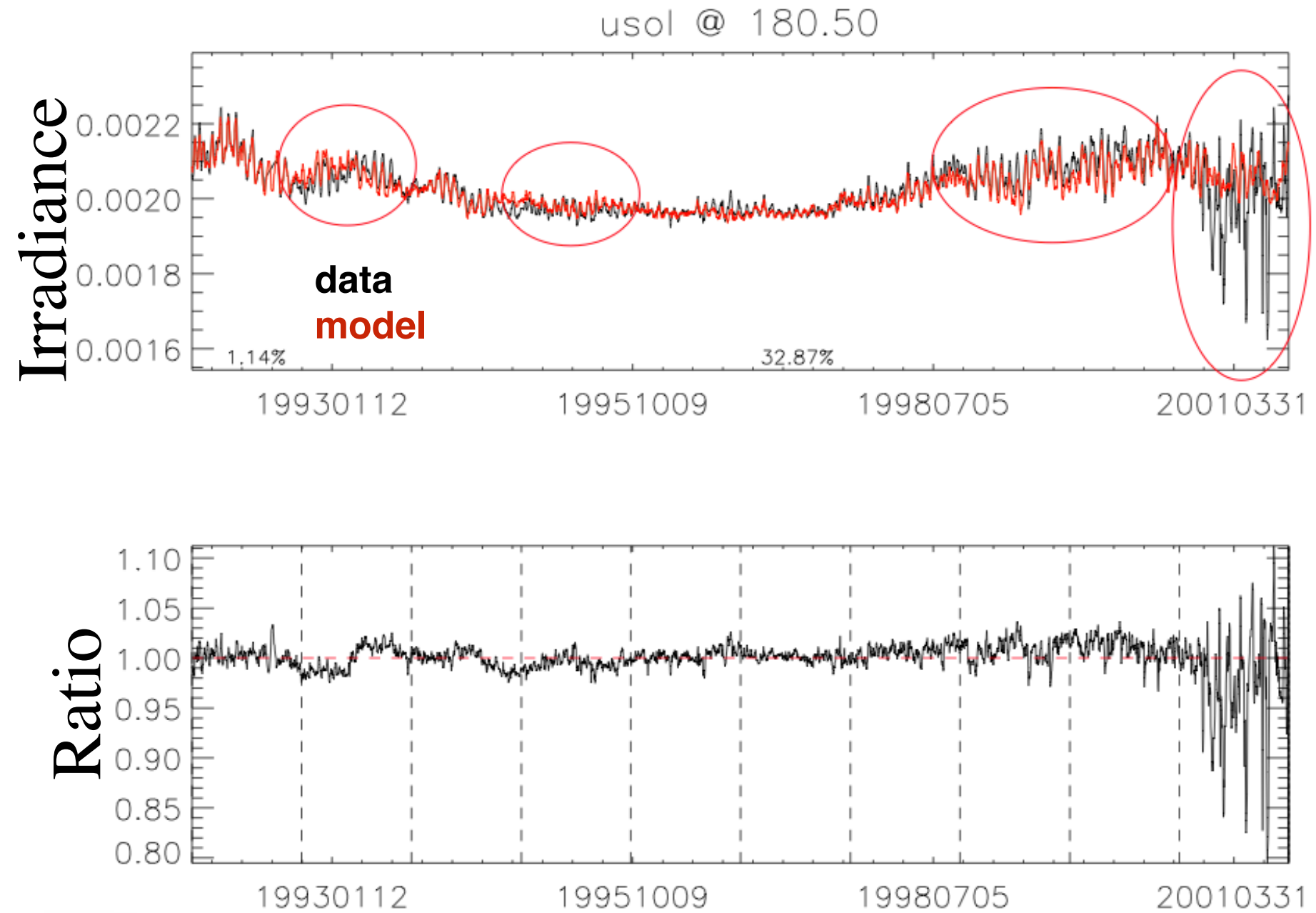
- Very good agreement



# How does it work ?

*Example: UARS/Solstice @ 180.5nm*

- Very good agreement
- Except at some time of the mission



Long term uncertainty ?

# How does it work ?

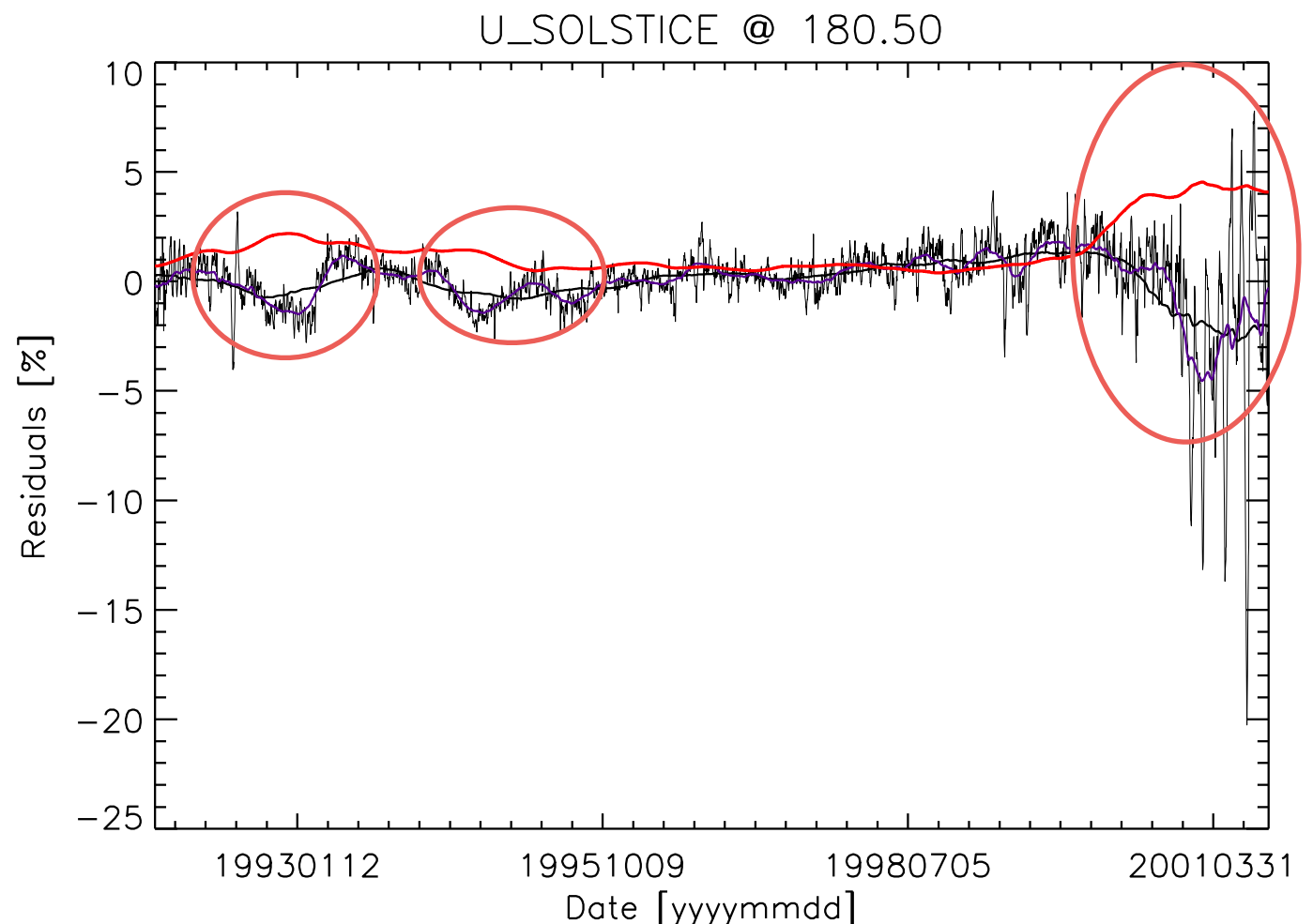
## *Example: UARS/Solstice @ 180.5nm*

$U(\lambda, t)$ : average disagreement in the yearly slope of the observed and modeled SSI

$$U(\lambda, t) = \text{smooth}_{1\text{-yr}} (||a_{obs}(\lambda, t) - a_{model}(\lambda, t)||)$$

with  $a(\lambda, t)$ : normalized slope of the time series computed over one year

- Uncertainty is about 0.5%/yr except where disagreement improves
- Snow+ (2010) estimated 0.5% / yr



# How does it work ?

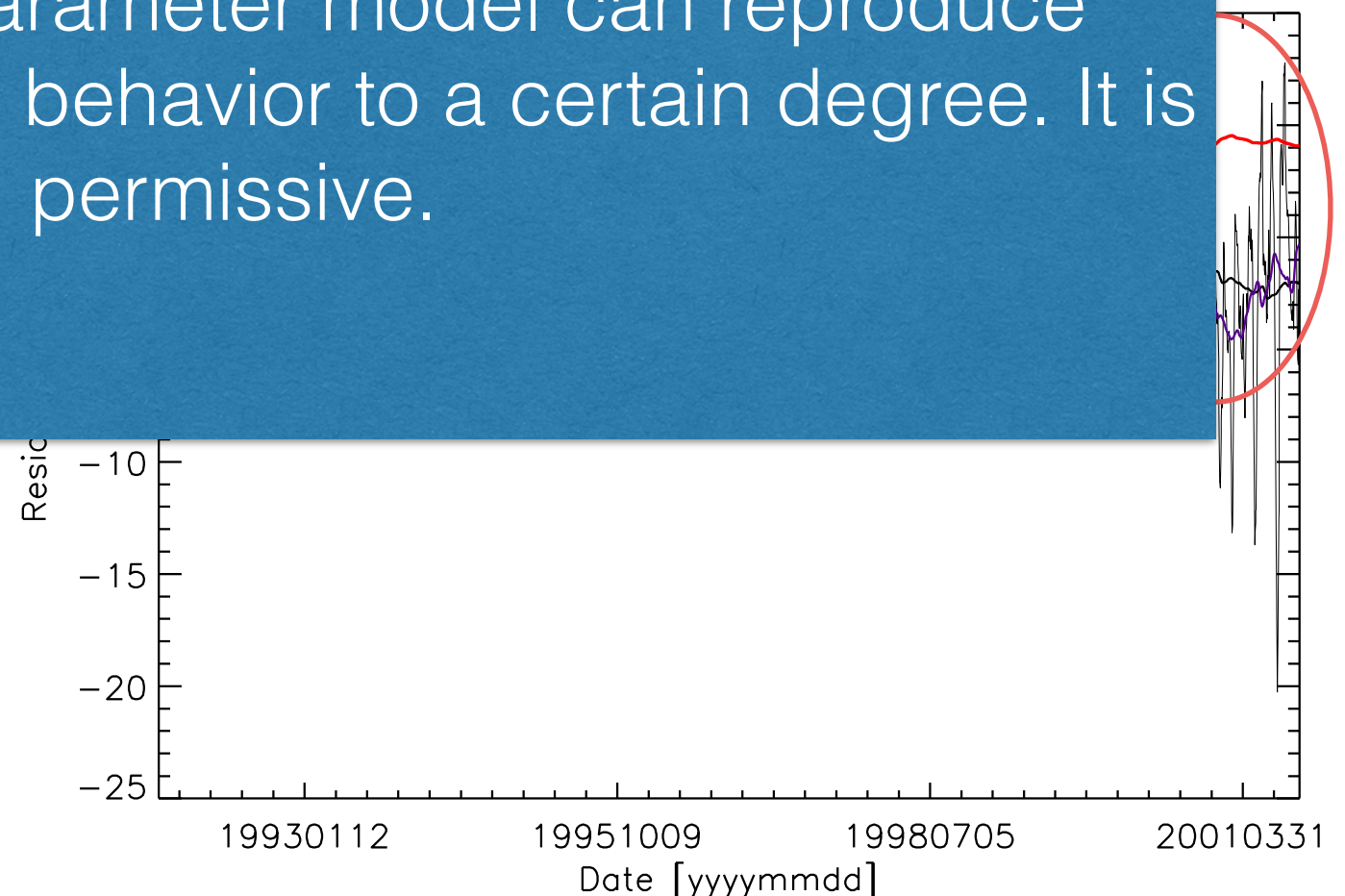
## Hyp. 2:

**What can not be reproduced by the two time scales proxy-model is more uncertain.**

cons: this multi parameter model can reproduce trends and non solar behavior to a certain degree. It is permissive.

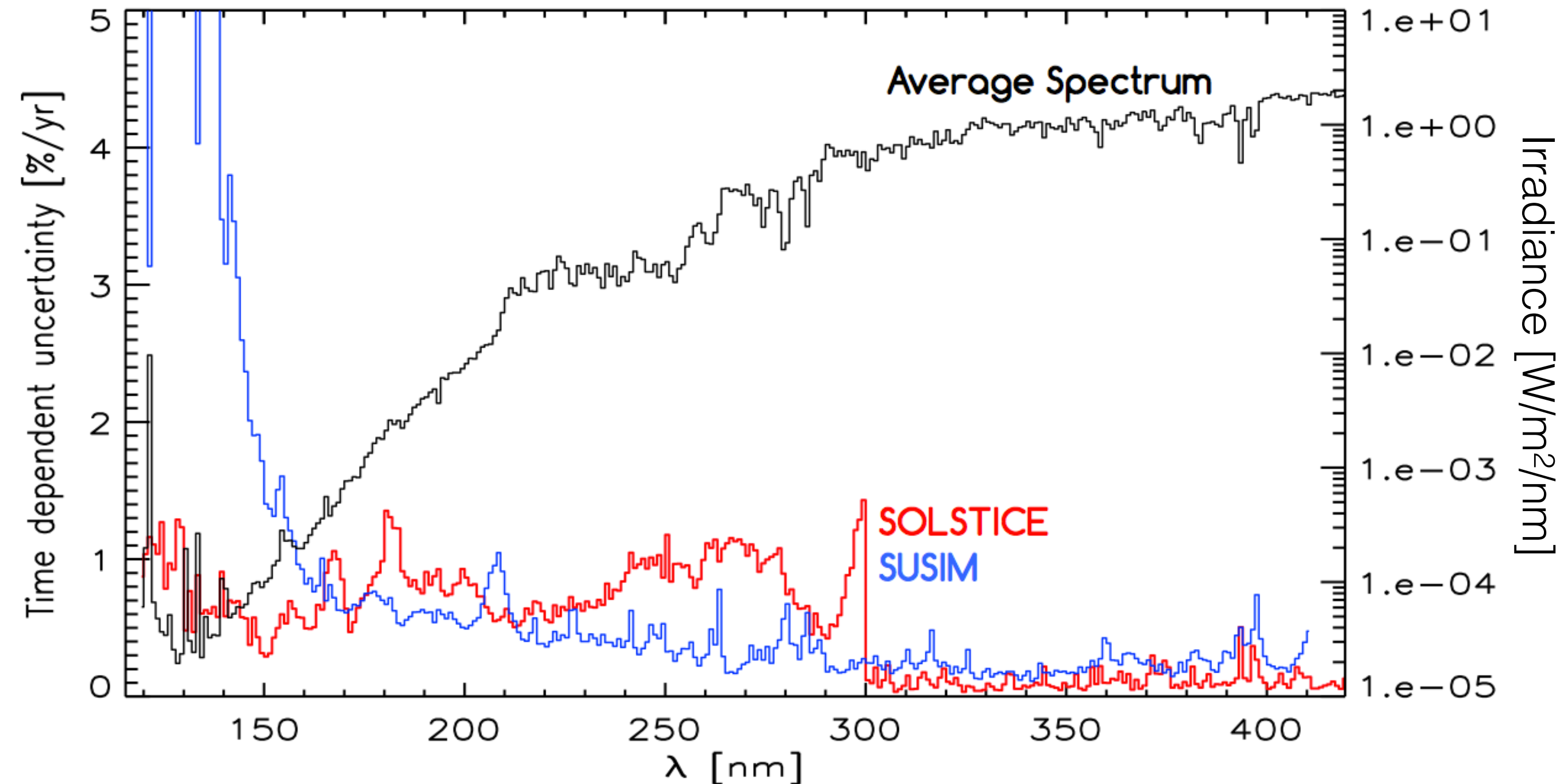
- Uncertainty  
0.5%  
when  
improves

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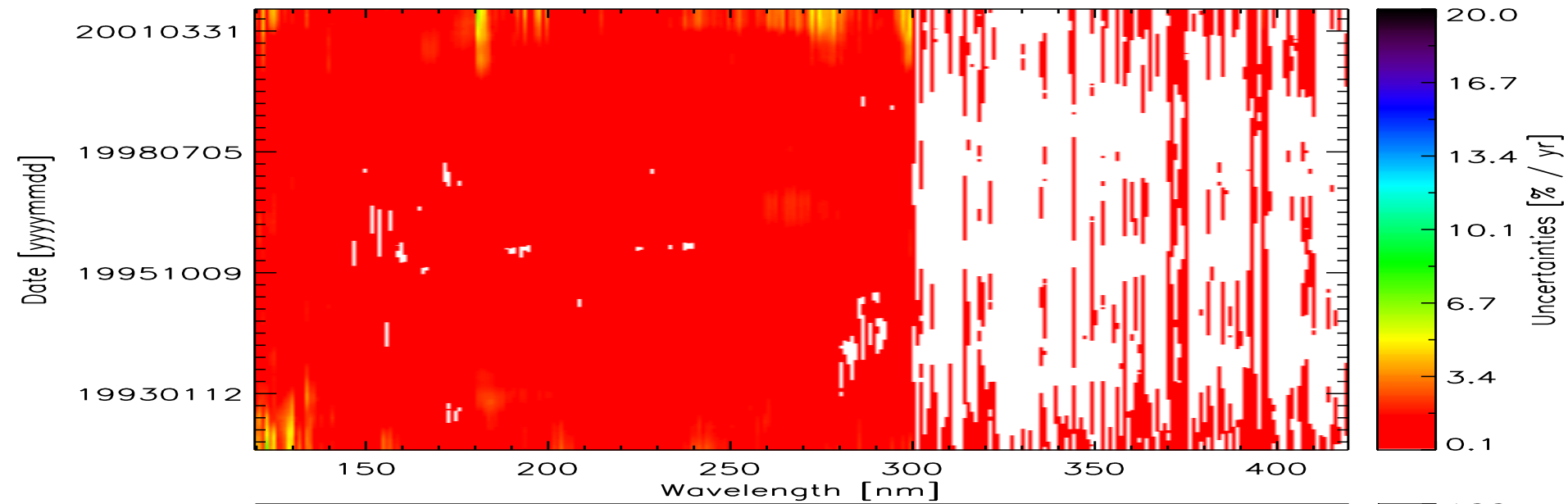
# UARS Overview



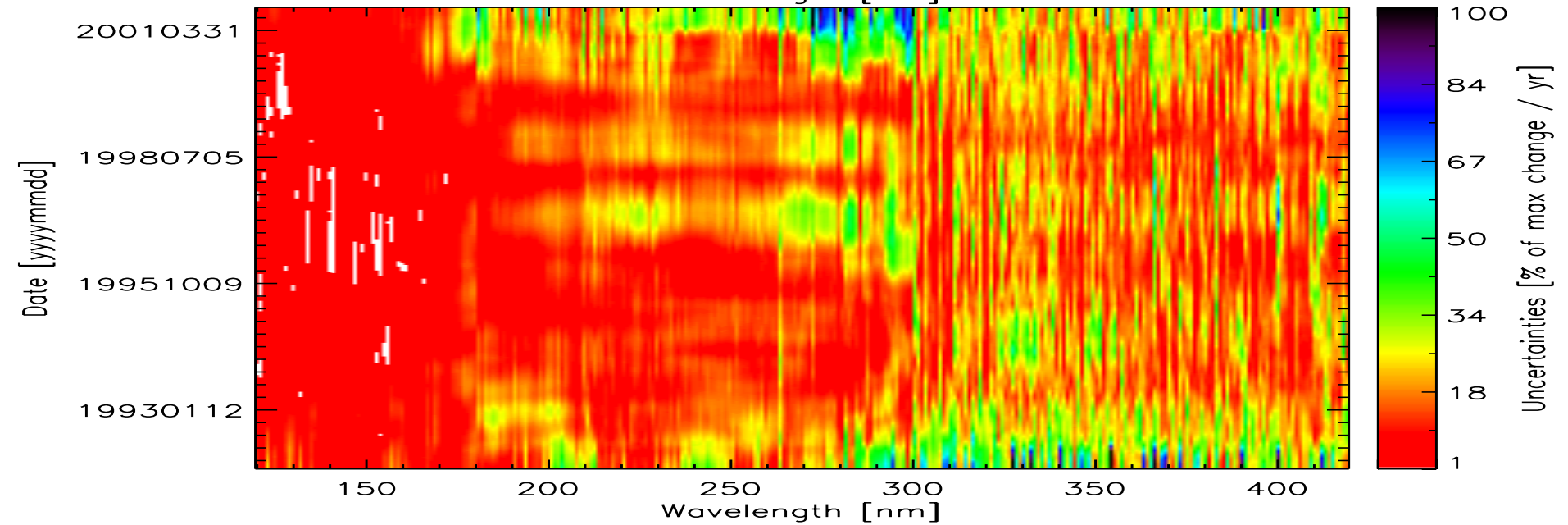
- The time dependent LTU are averaged over the mission lifetime

# UARS / SOLSTICE

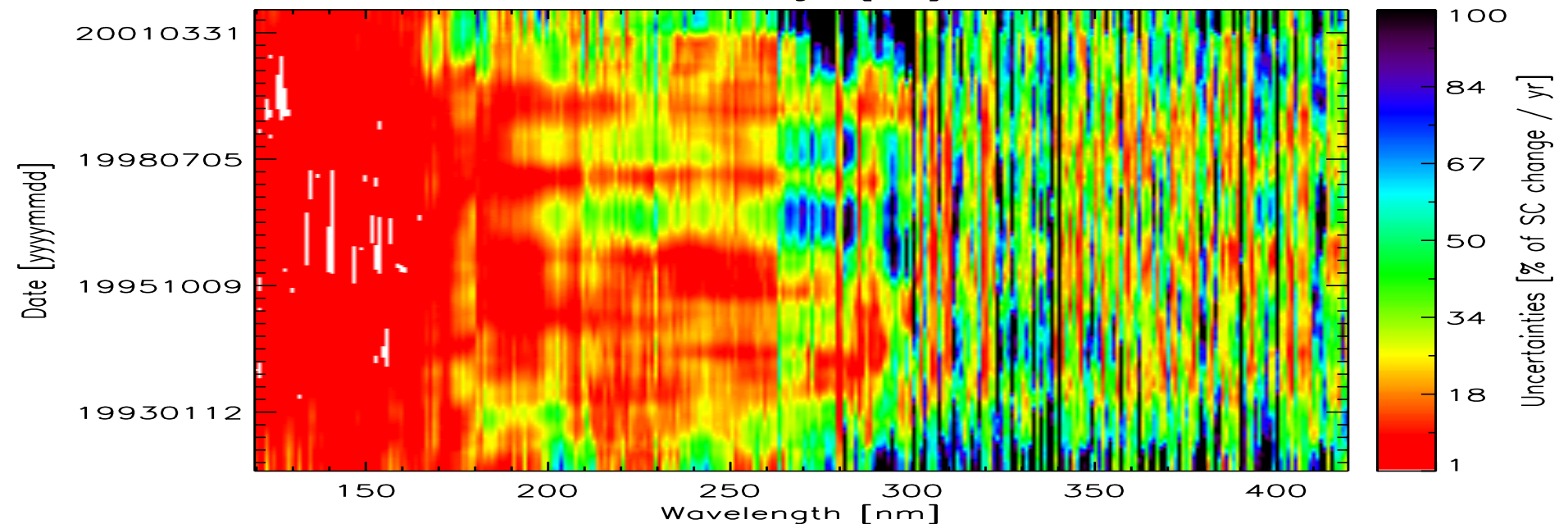
- LTU in % / yr



- LTU in % of maximum variation / yr

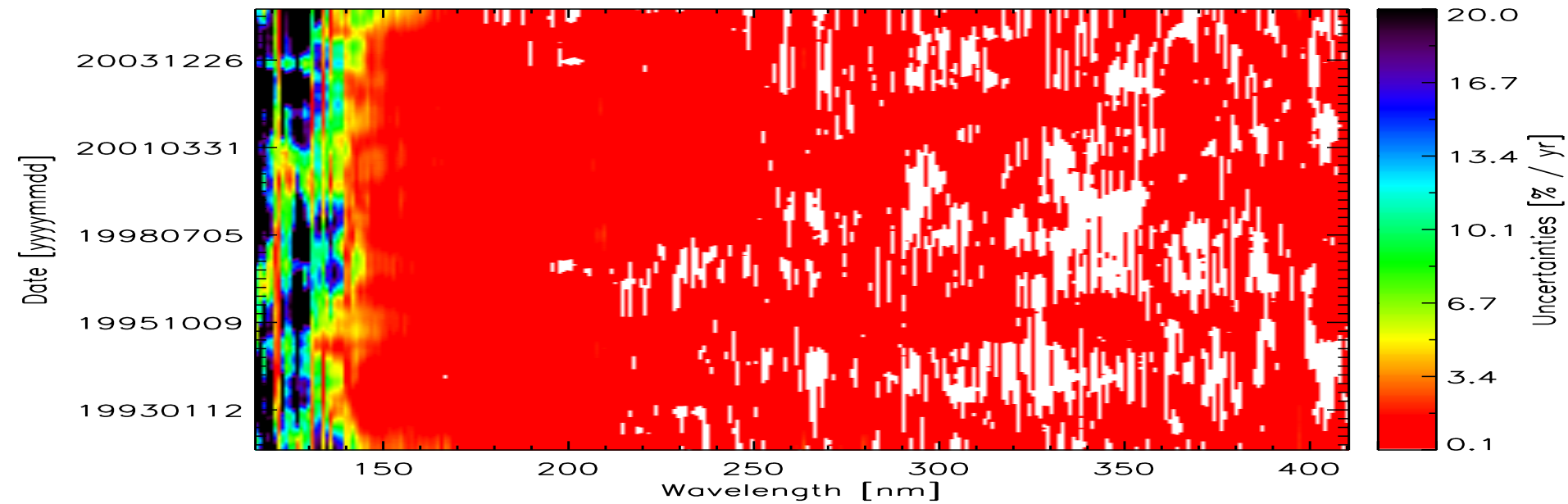


- LTU in % of solar cycle variation / yr

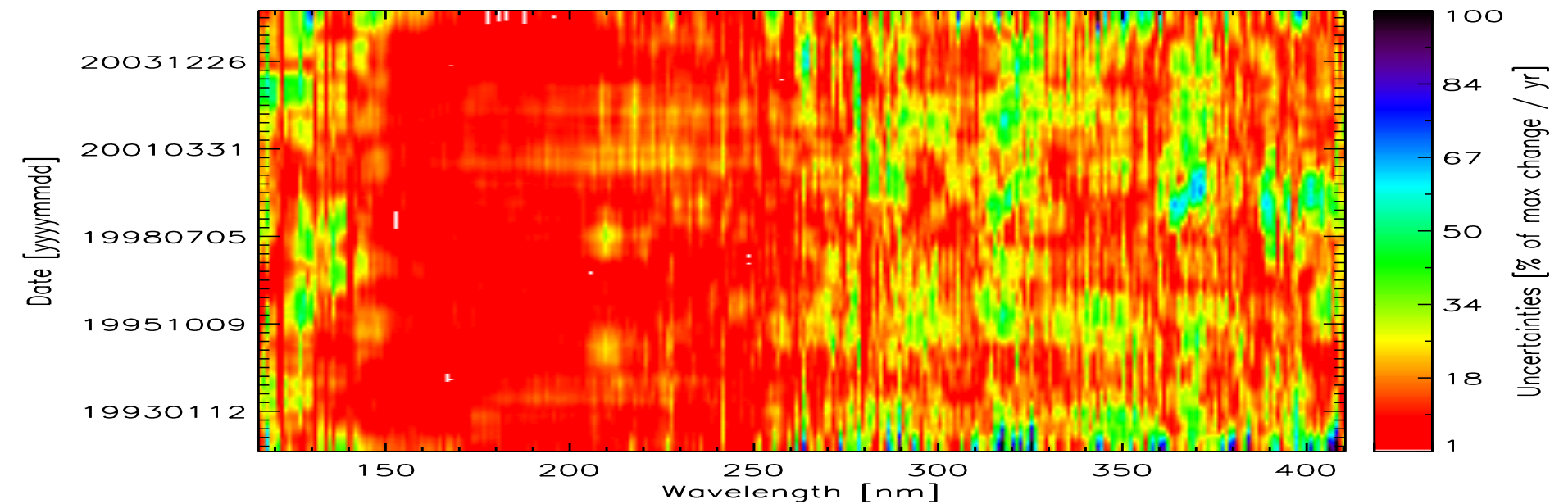


# UARS / SUSIM

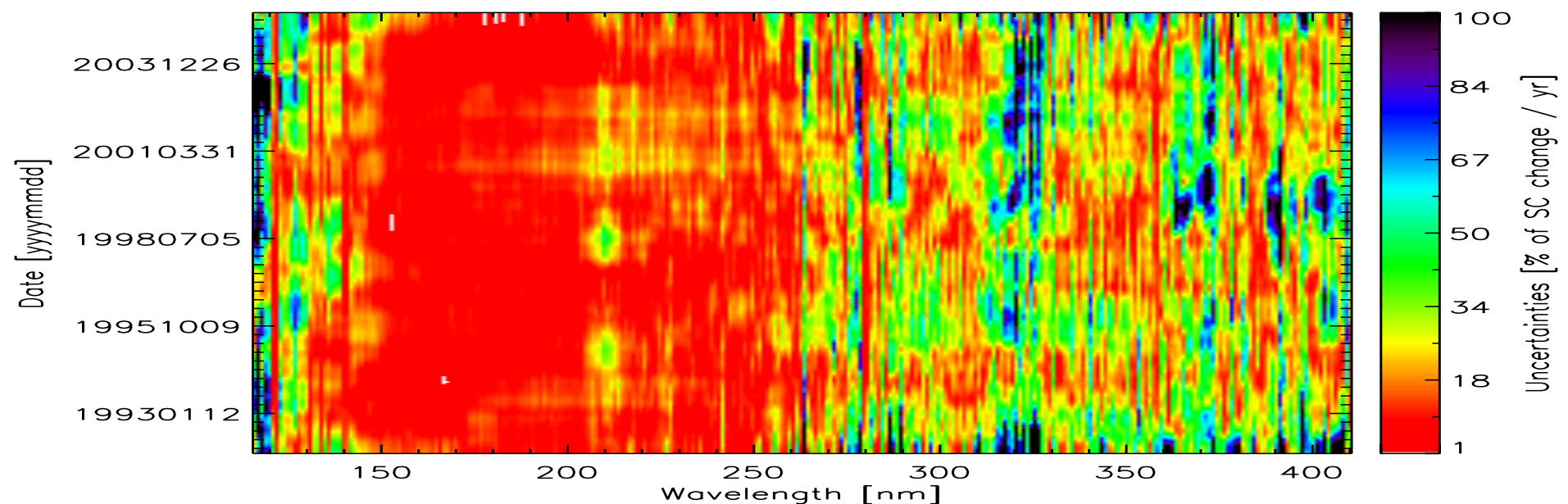
- LTU in % / yr



- LTU in % of maximum variation / yr

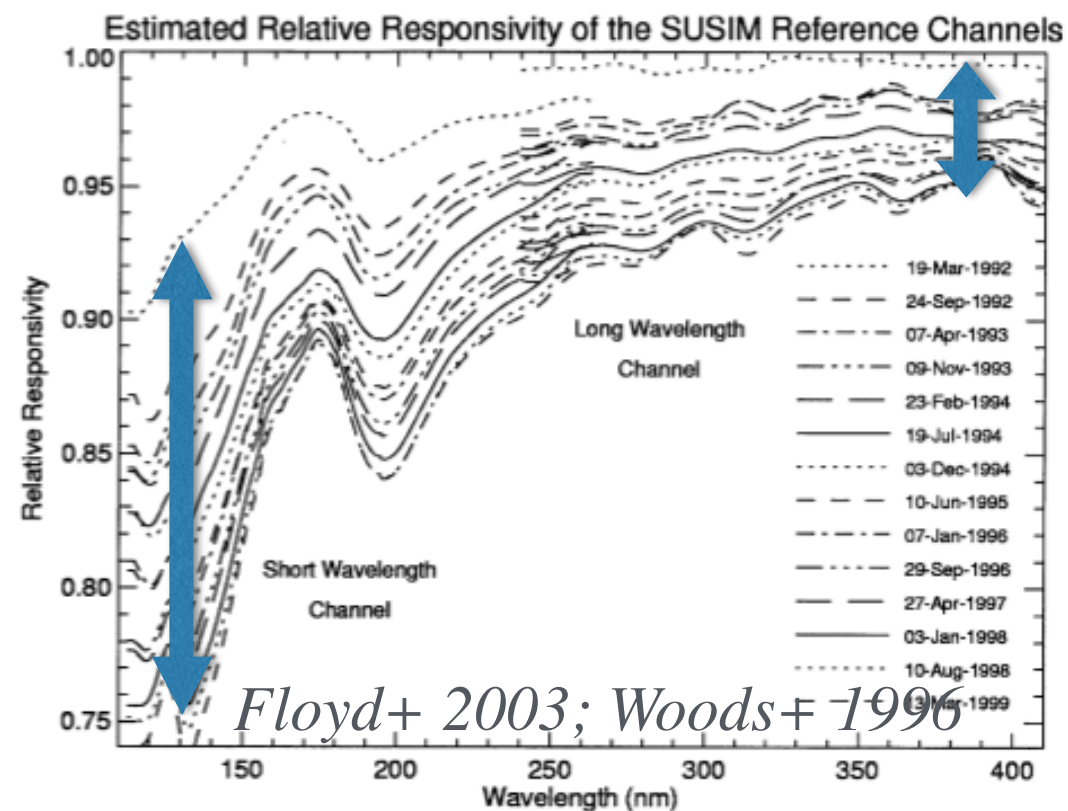
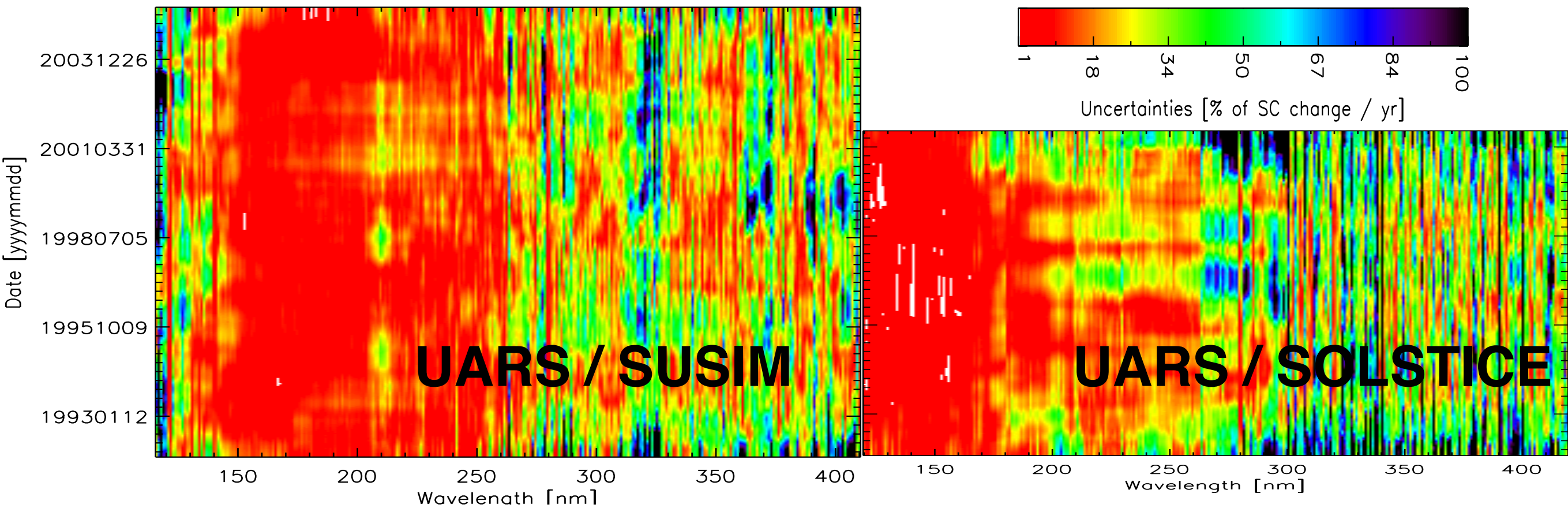


- LTU in % of solar cycle variation / yr

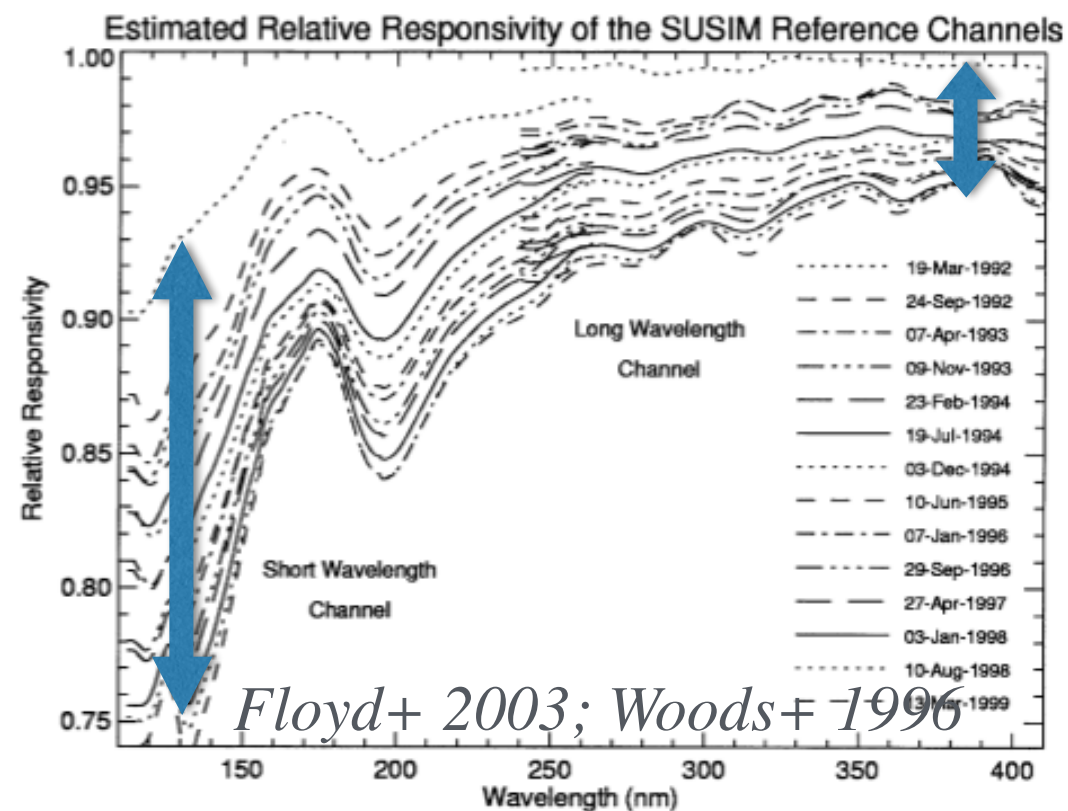
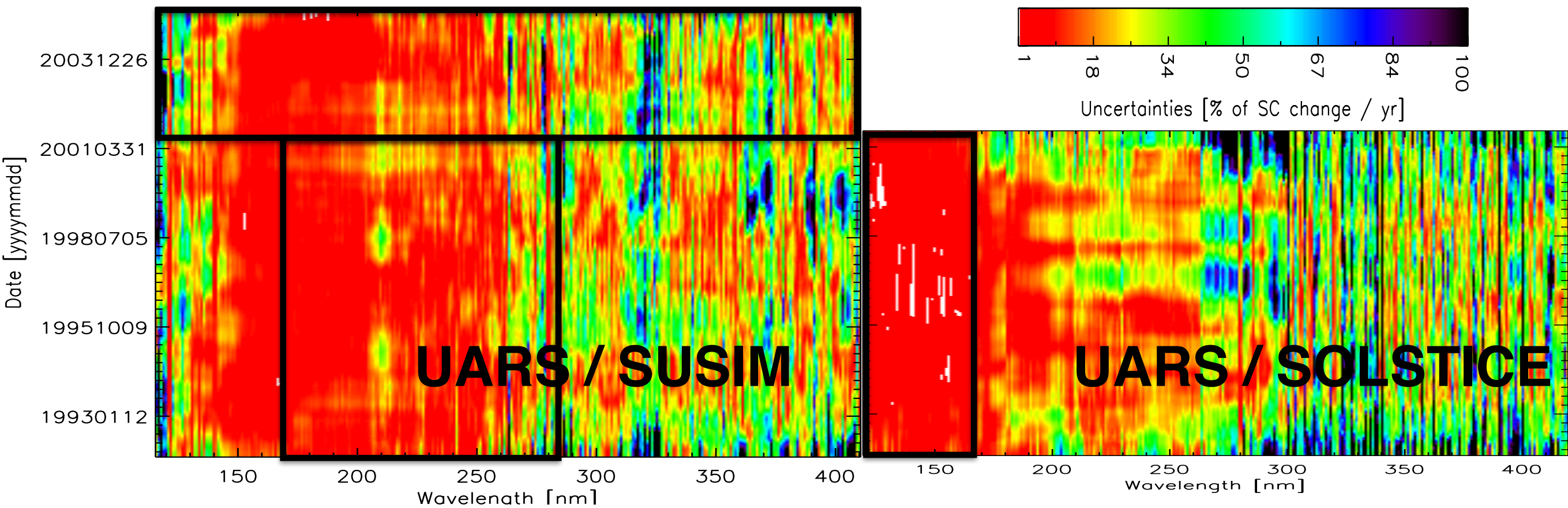




# U\_SUSIM vs U\_SOLSTICE

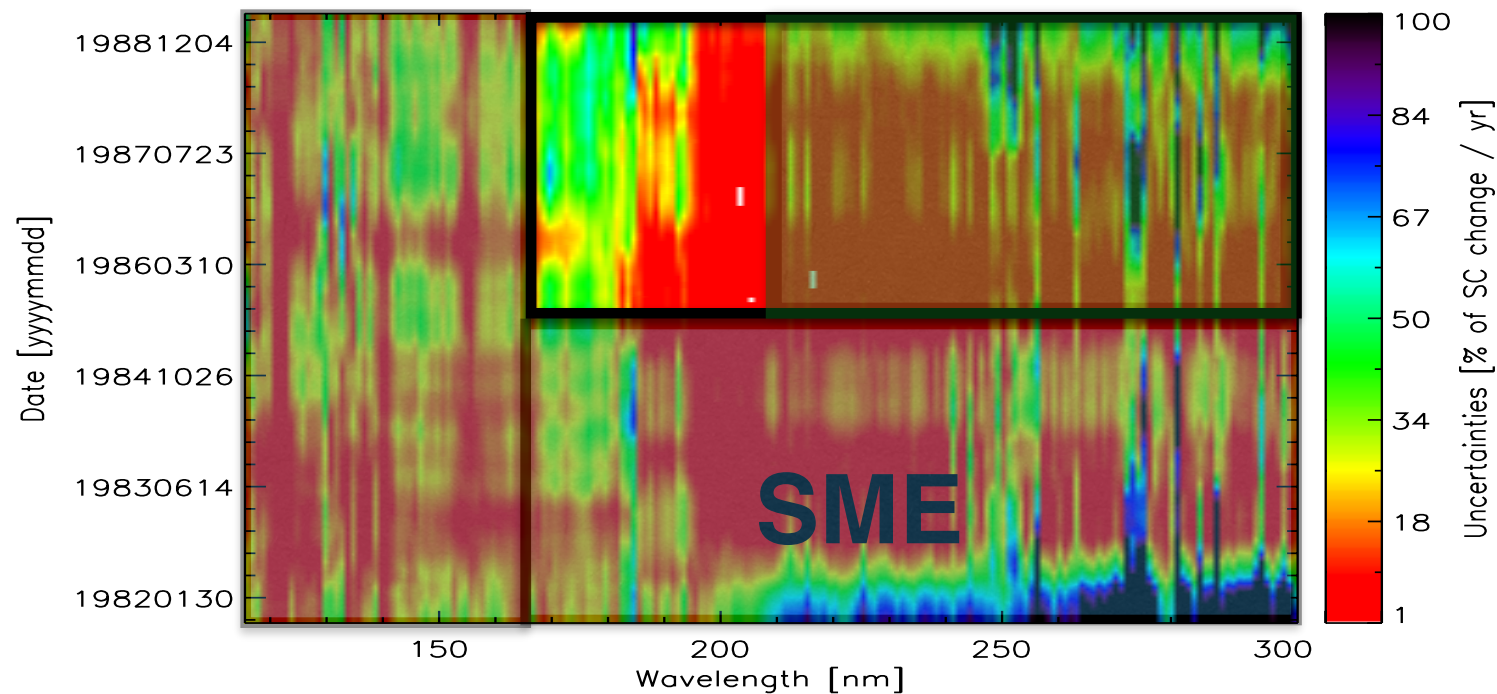
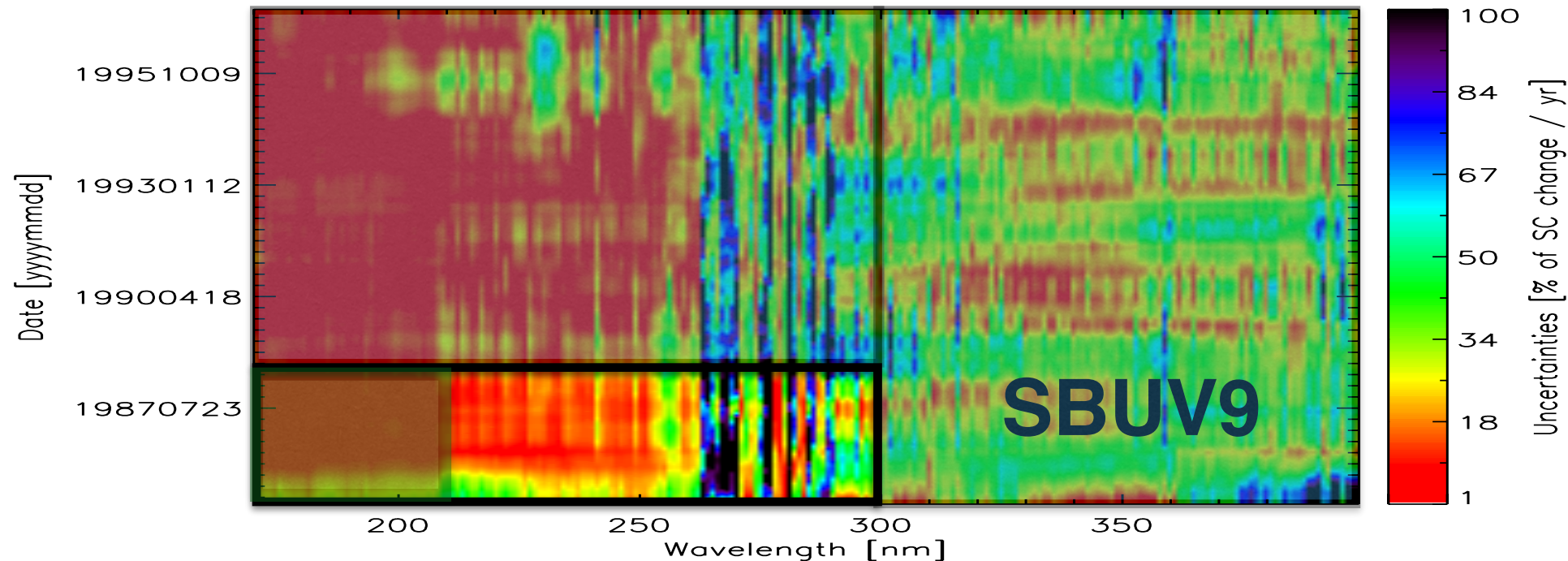


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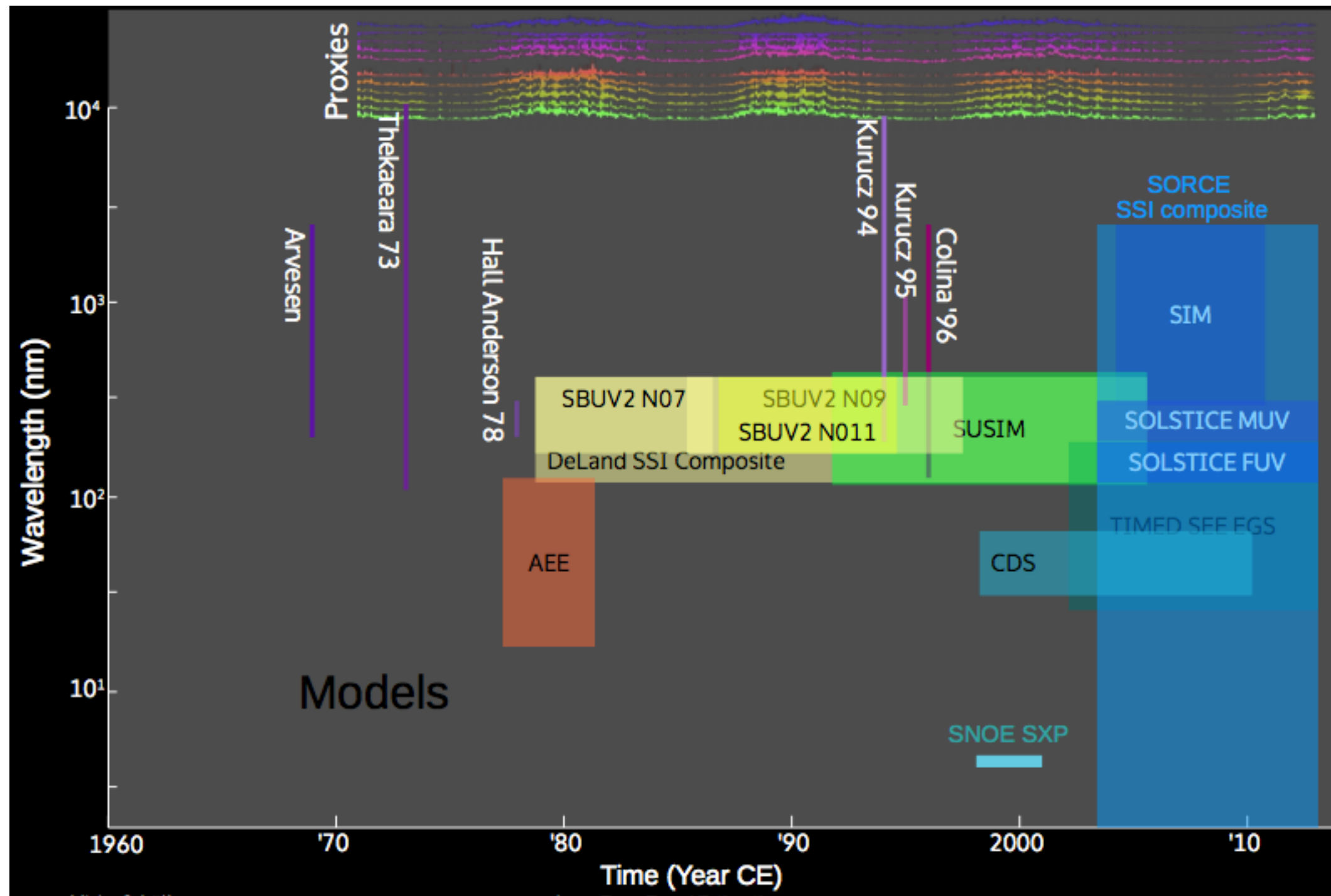


# SME & SBUV9

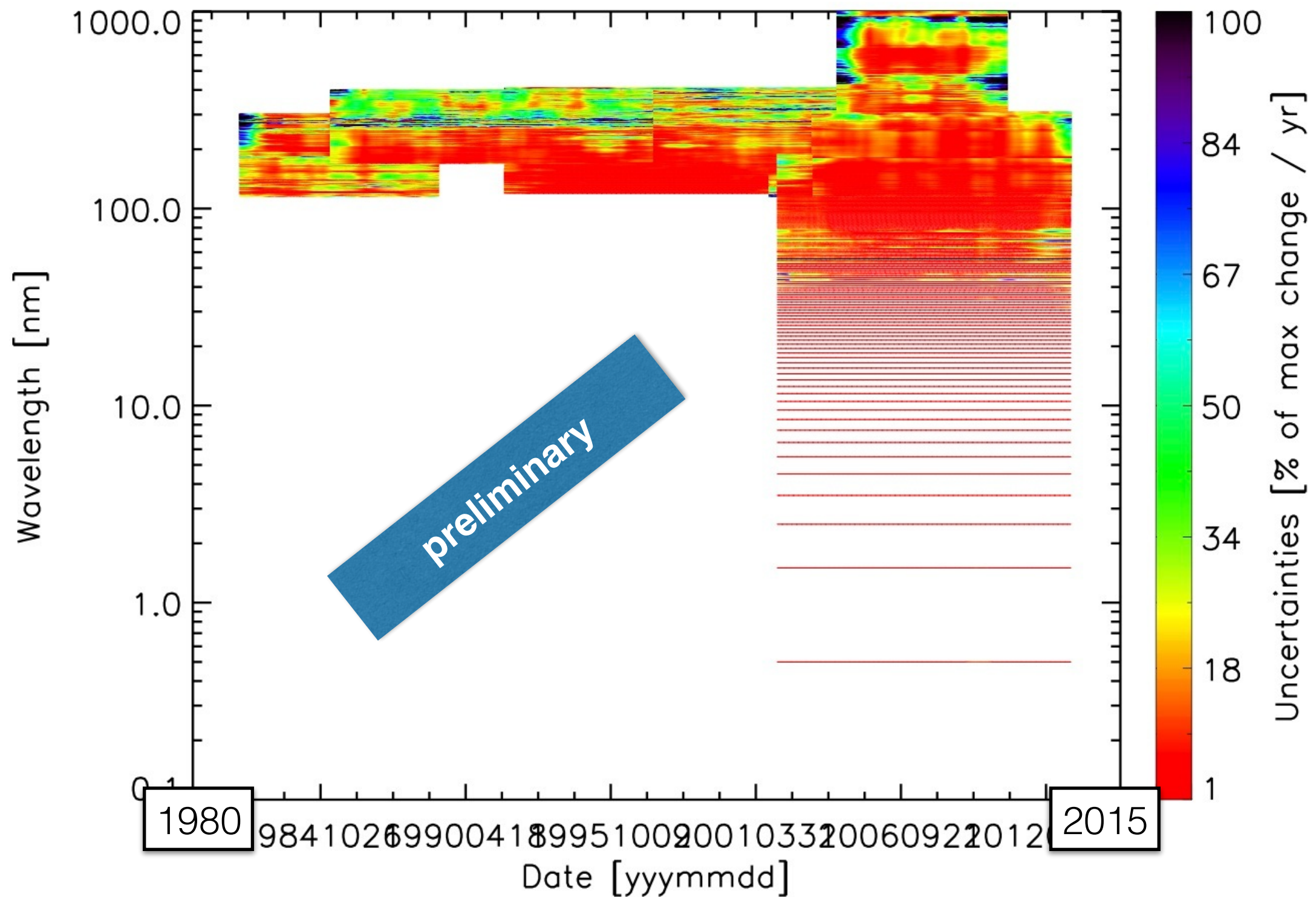


- **Not definitive:**
  - ➔ Other SBUV data available.
  - ➔ Degradation of SBUV's response corrected using proxies...

# General Overview

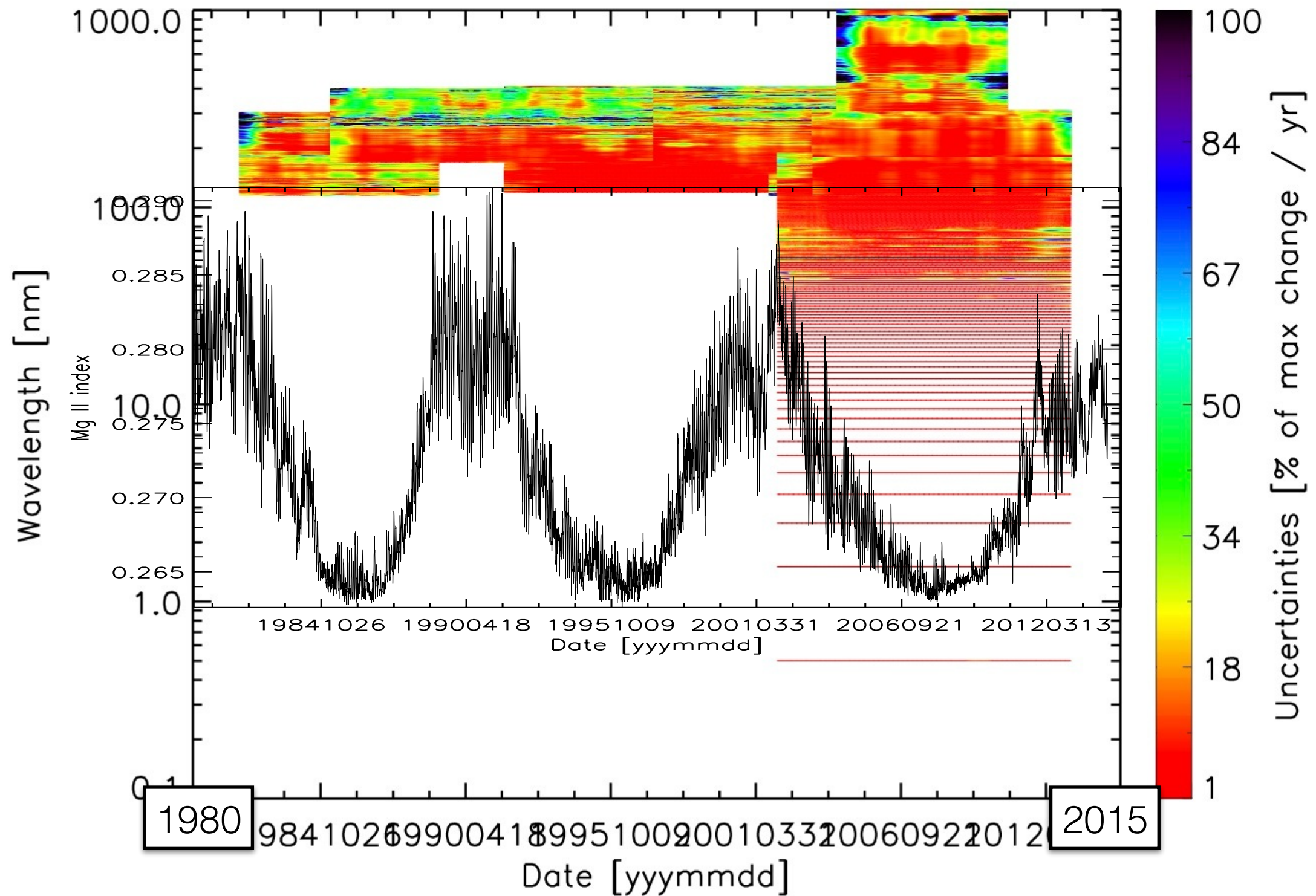


# General Overview





# General Overview



# The less permissive

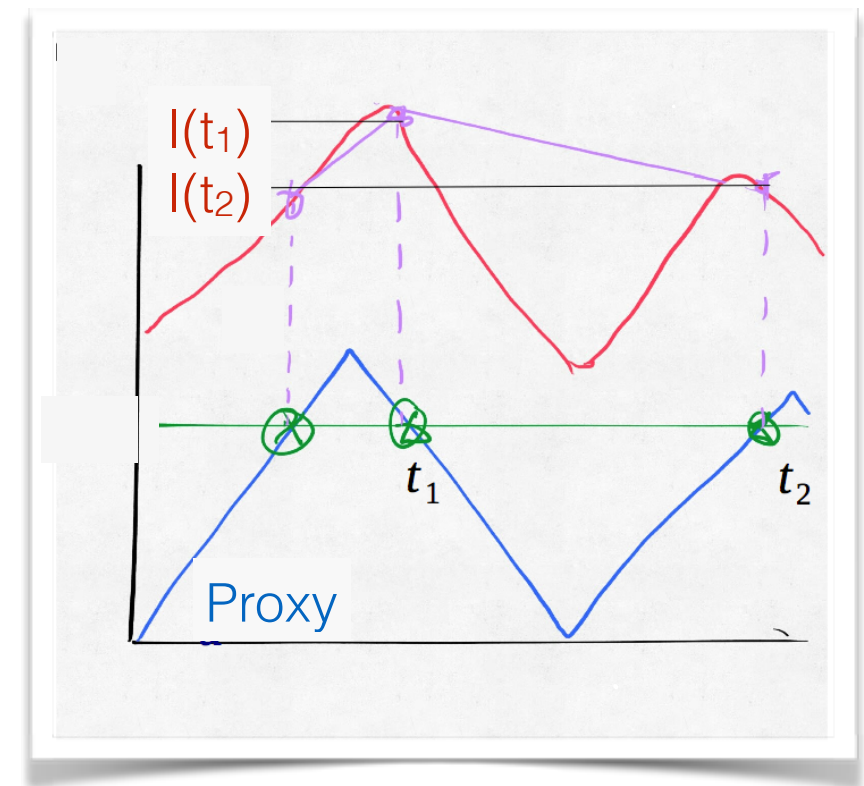
- Unfortunately there is residual degradation in the observed values

$$I^{meas}(t) = I^{true}(t)g(t)$$

- Assume an unknown but exact proxy model:

$$I^{true}(t) = f(p(t)) + \text{X}$$

$$p(t_1) = p(t_2) \rightarrow I^{true}(t_1) = I^{true}(t_2) + \text{X}$$





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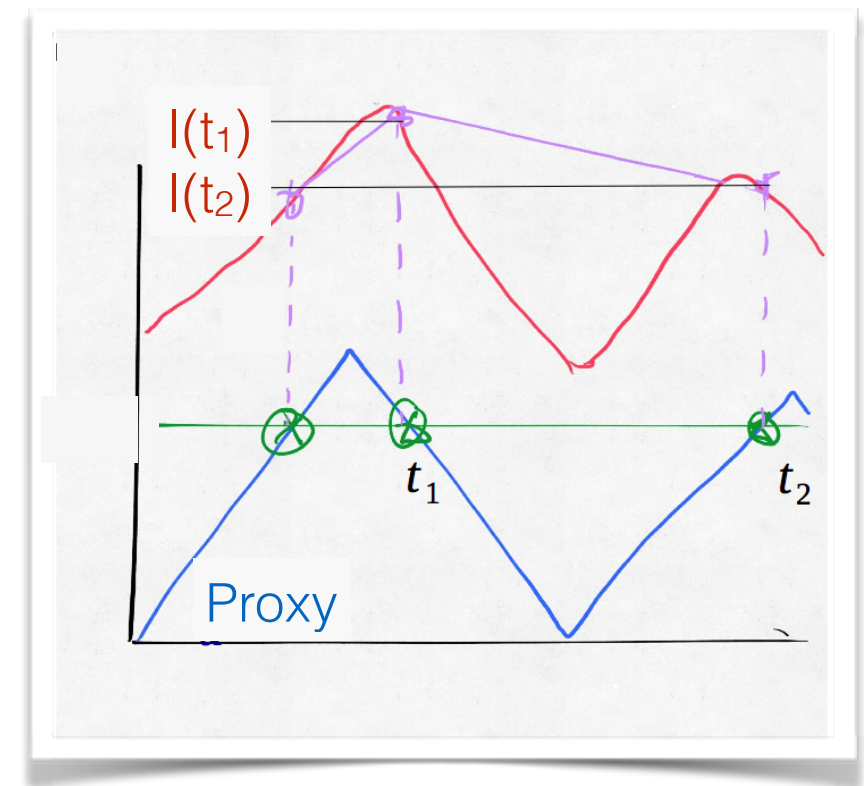
$$I^{true}(t) = f(p(t)) + \text{✗}$$

$$p(t_1) = p(t_2) \rightarrow I^{true}(t_1) = I^{true}(t_2) + \text{✗}$$

$$\frac{I^{meas}(t_1)}{I^{meas}(t_2)} = \frac{I^{true}(t_1)g(t_1)}{I^{true}(t_2)g(t_2)} \approx \frac{g(t_1)}{g(t_2)} + \text{✗}$$

$$g(t) = a_0 + a_1t + a_2t^2 + \dots$$

$$g(t=0) = 1$$



# The less permissive

• Unf  
valu

erved

Hyp. 2:

if  $p(t_1) = p(t_2)$  then  $I(t_1) = I(t_2)$

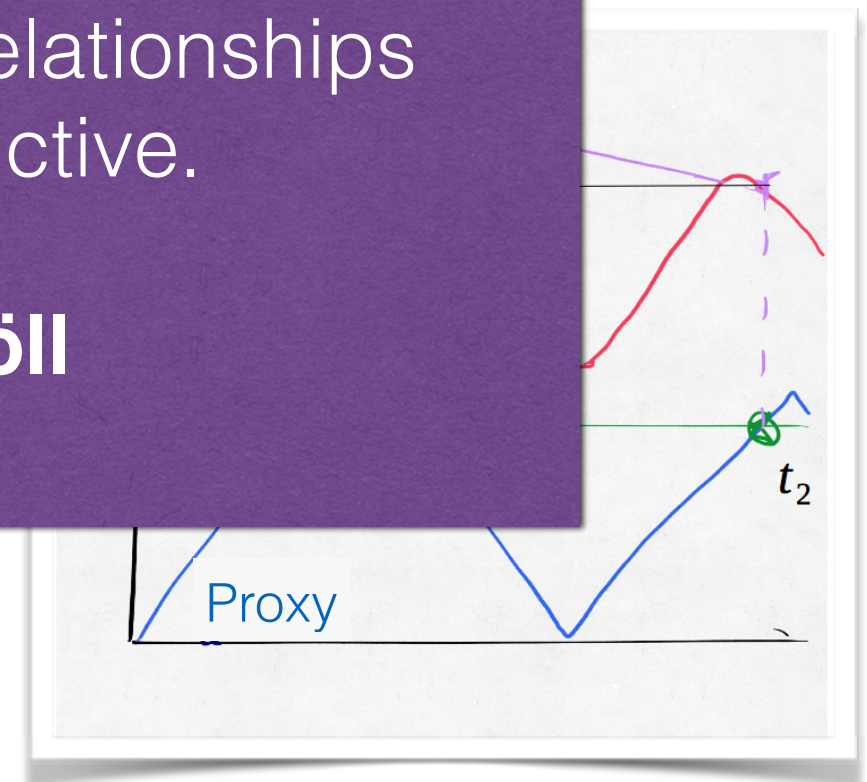
cons: no phase shift, no change in relationships between proxy and I. It is restrictive.

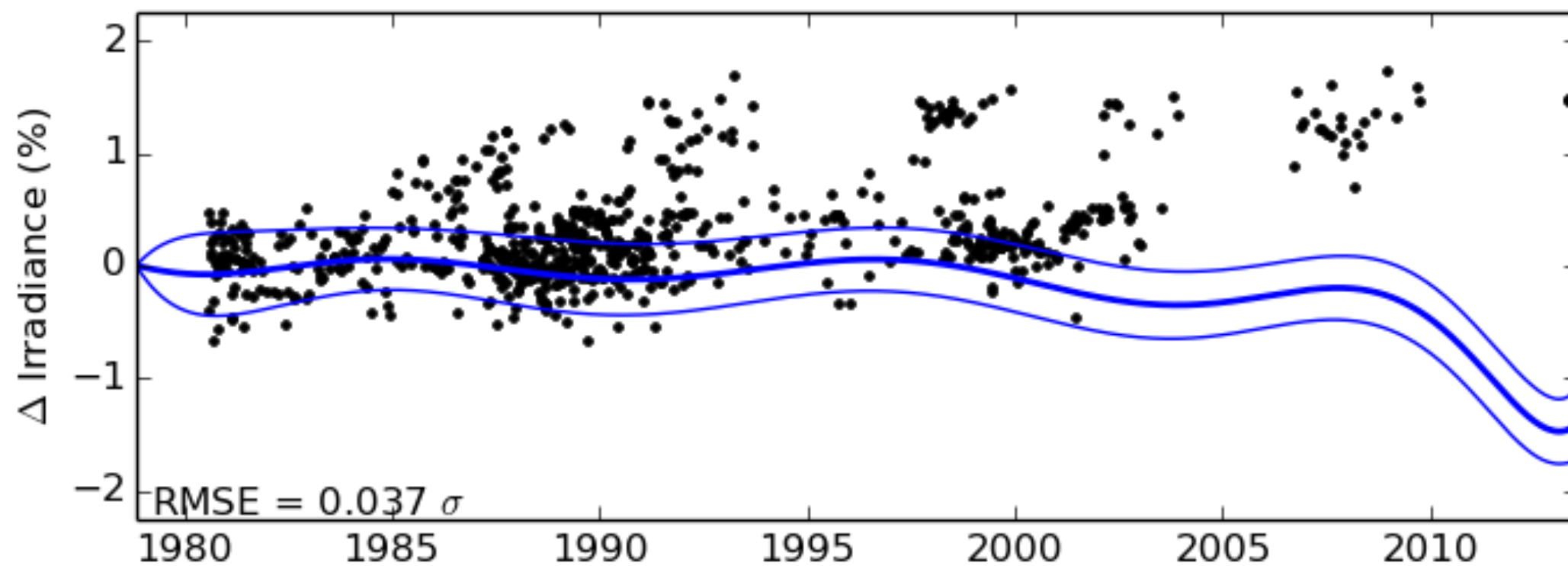
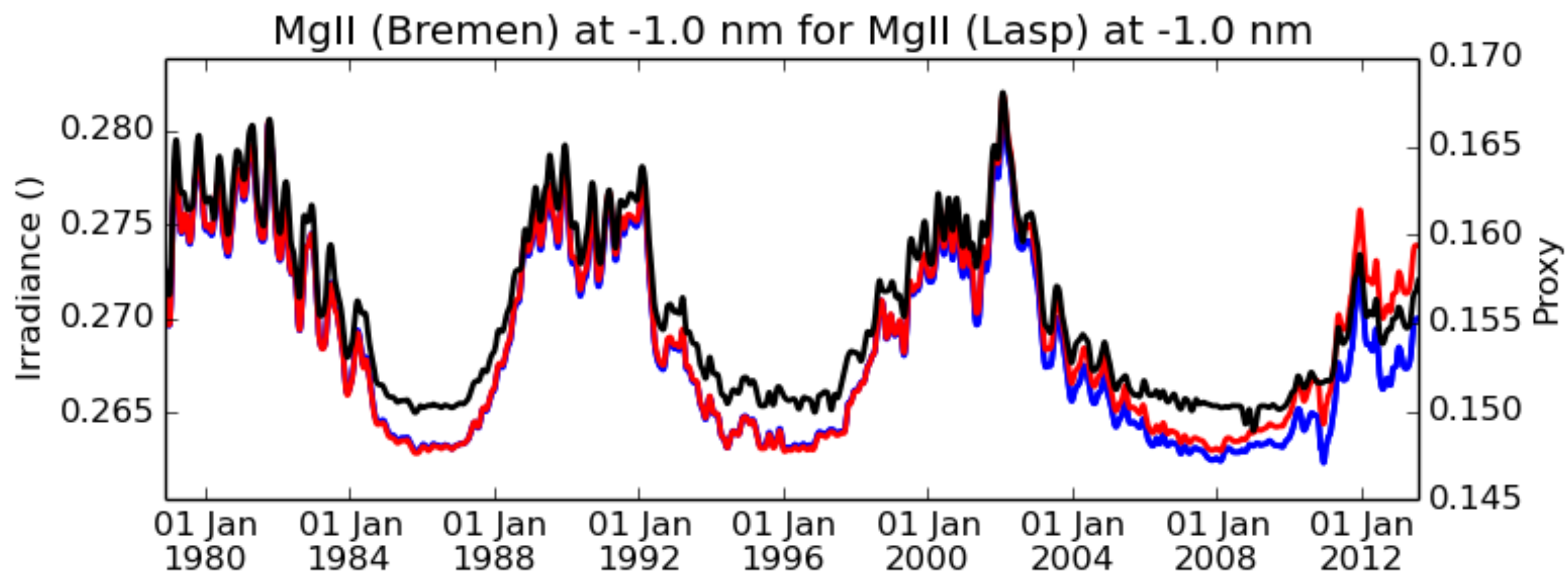
See poster by Micha Schöll

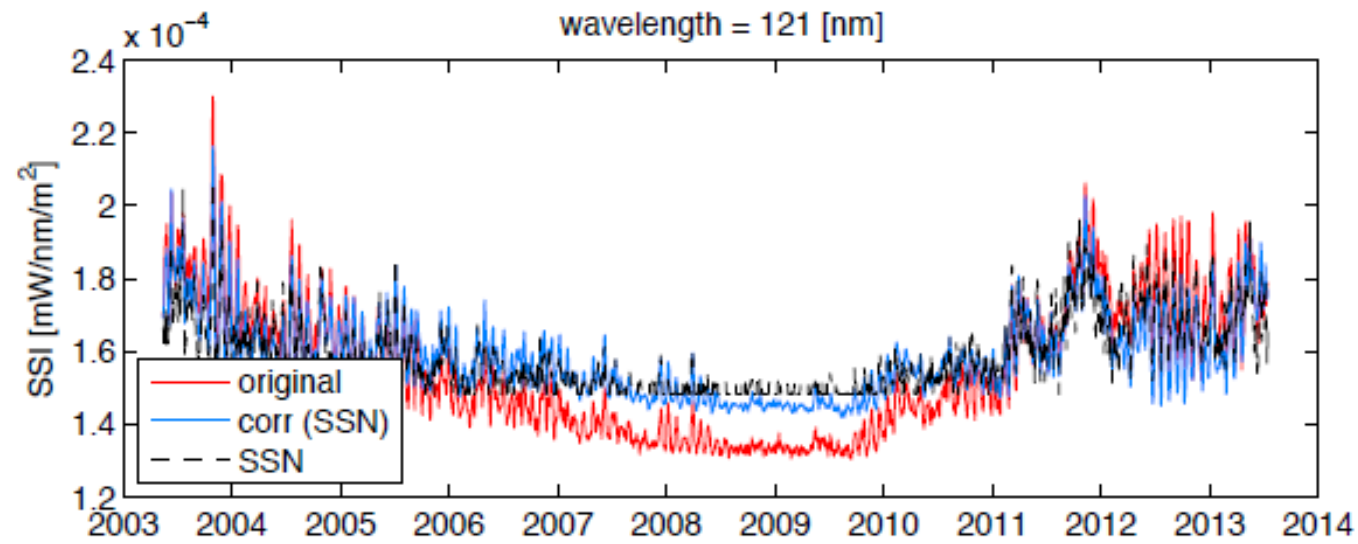
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$$g(t) = a_0 + a_1 t + a_2 t^2 + \dots$$

$$g(t=0) = 1$$

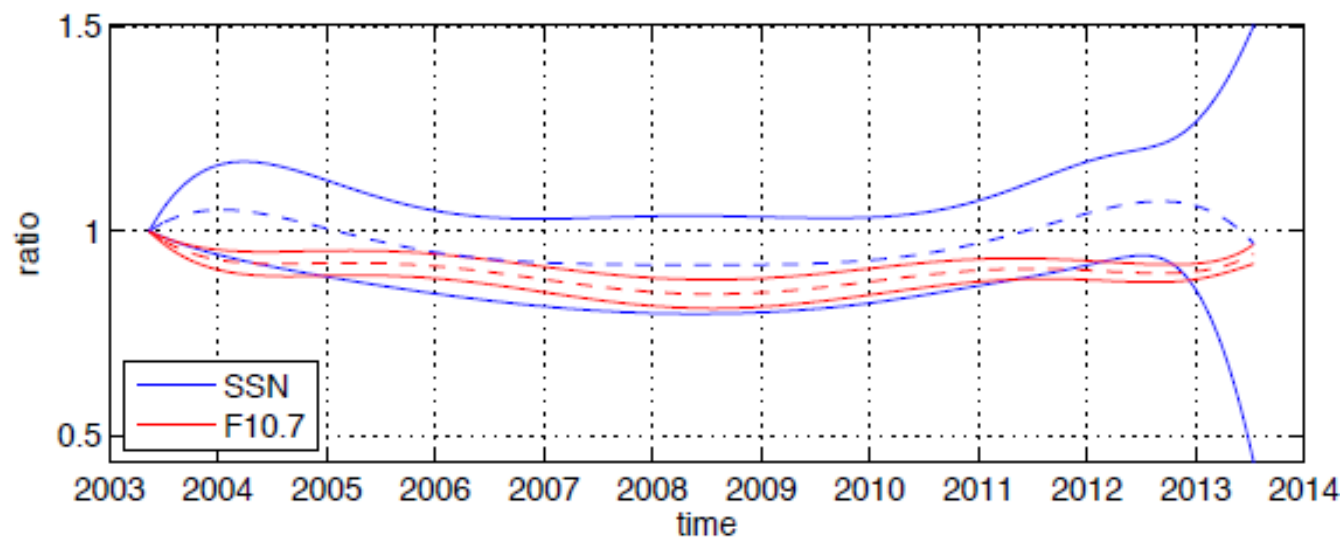
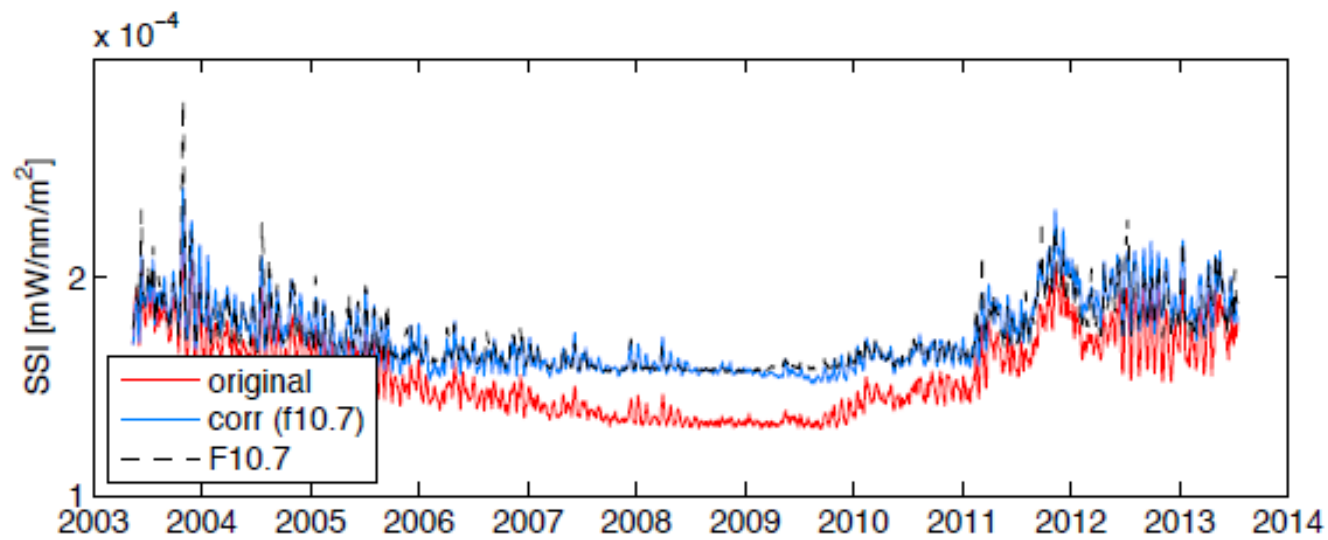




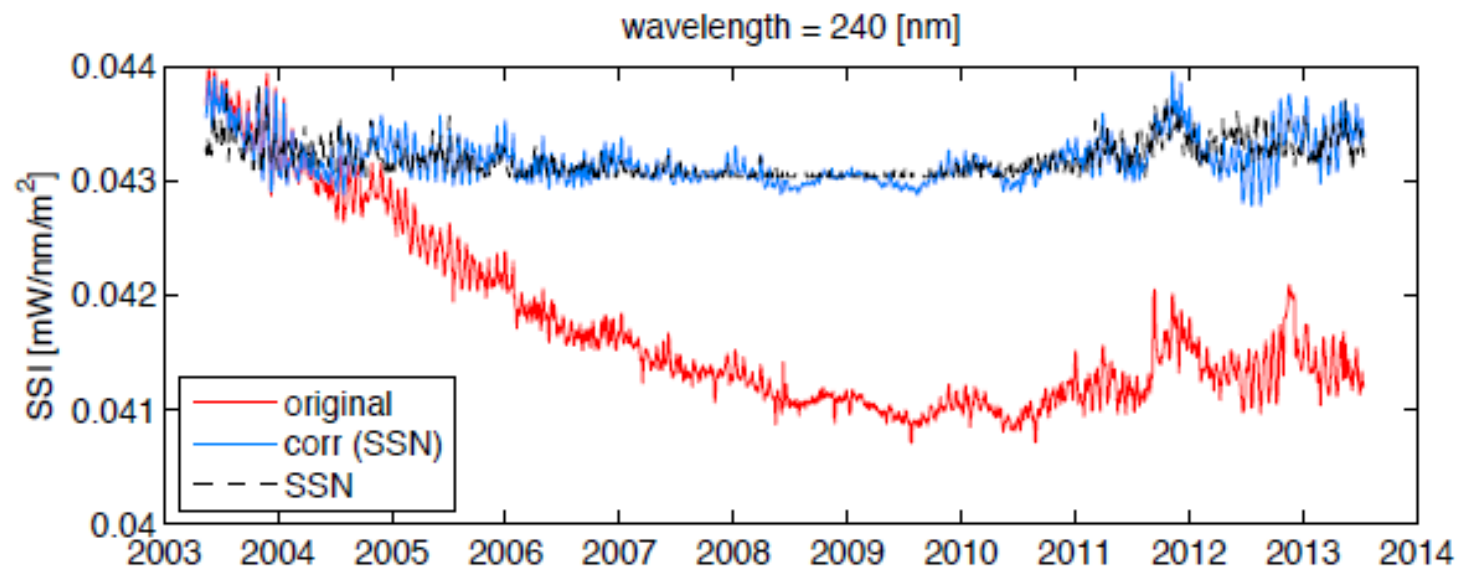


SOLSTICE Trend  
correction for Ly-a (121  
nm)

Using SSN and F10.7 as  
equal activity indicators  
(EQA)

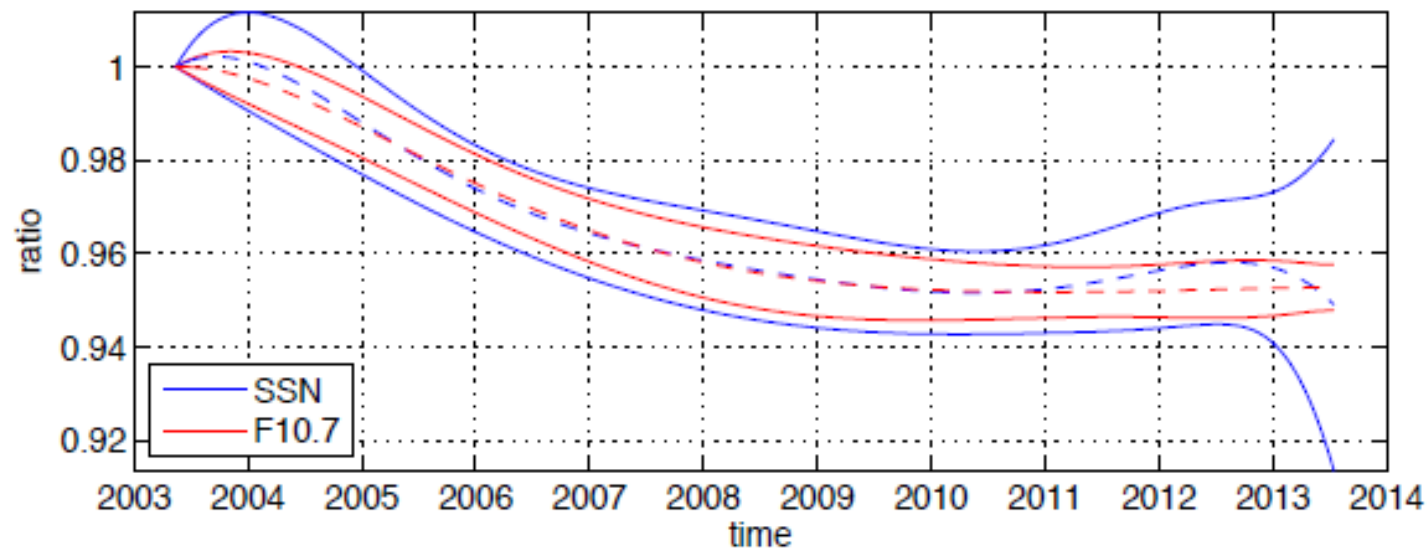
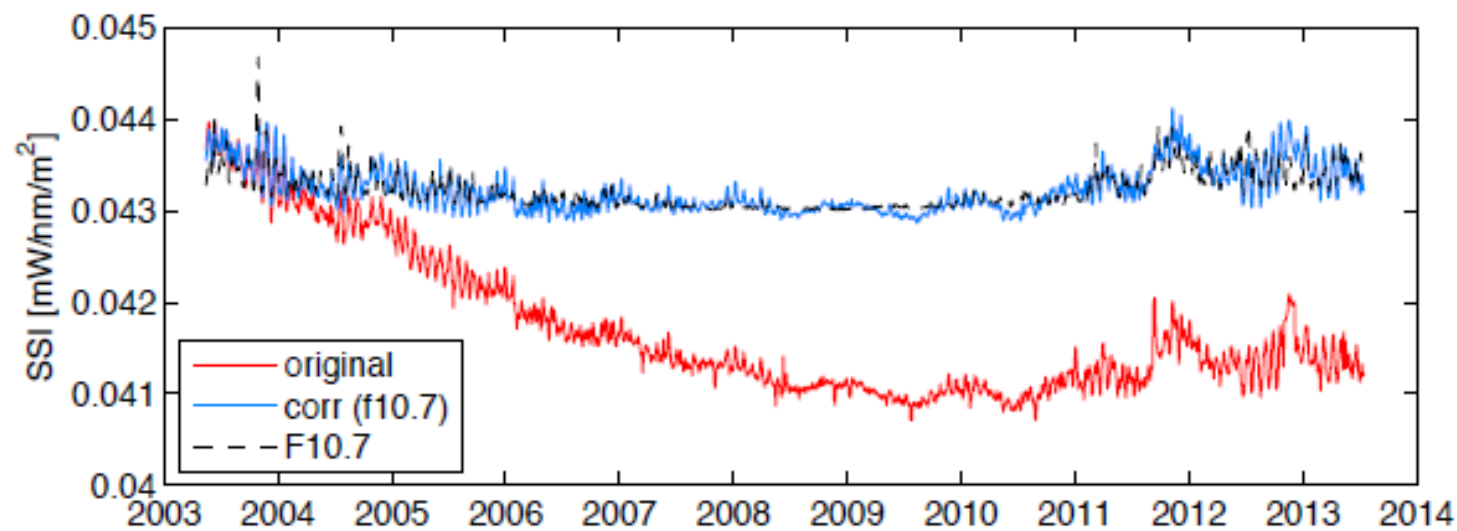






SOLSTICE Trend  
correction for 240 nm

Using SSN and F10.7 as  
equal activity indicators  
(EQA)



# Conclusions

- Long term uncertainties is essential. Should be time dependent
- Two time-scale proxy model:
  - ➔ simple and robust. Time dependent.
  - ➔ give value in agreement with instrumental value.
  - ➔ permissive
- « if  $p(t_1) = p(t_2)$  then  $I(t_1)=I(t_2)$  » method
  - ➔ strong assumptions
  - ➔ give results in agreement to « what is expected »

**THANK**

**YOU**